

A Model of Spatial Directness in Interactive Visualization

Stefan Bruckner, Tobias Isenberg,
Timo Ropinski, Alexander Wiebel

University of Bergen, Norway

Inria / Université Paris-Saclay, France

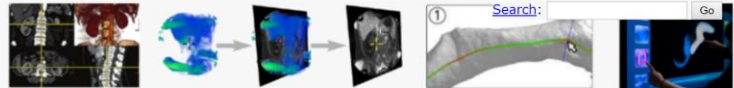
Ulm University, Germany

University of Applied Sciences Worms, Germany

Motivation


<http://tutorials.awmw.org/DirectVolumeInteraction>

Direct Volume Interaction



HomePage
Tutorials
EG 2015
Introduction
Part 1
Part 2
Part 3
Part 4
VIS 2015
Introduction
Part 1
Part 2
Part 3
Part 4
Contact

Direct Volume Interaction for Visual Data Analysis



Thanks to all attendees who asked so many interesting questions and made the tutorial a success.

Schedule

Venue: [IEEE VIS 2015](#) in Chicago, USA

Link: <http://ieevis.org/year/2015/info/overview-amp-topics/tutorials#VOLUME>

Date: Sunday, 2015-10-25

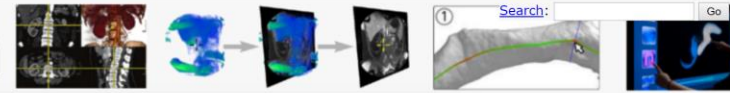
Room: Monroe, Palmer House Hilton

- 14:00
- 14:00-14:05 [Introduction](#) (Timo Ropinski)
- 14:05-14:45 **Part 1: [Visualization of Volume Data and the Need of Interaction](#)** (Timo Ropinski)
- 14:45-14:50 Questions
- 14:50-15:30 **Part 2: [Direct Manipulation](#)** (Alexander Wiebel)
- 15:30-15:40 Questions and discussion
- 15:40-16:15 **Break**
- 16:15-16:55 **Part 3: [Data Exploration on Novel Interaction Platforms](#)** (Tobias Isenberg)
- 16:55-17:00 Questions
- 17:00-17:40 **Part 4: [Visual Exploration and Guided Navigation](#)** (Stefan Bruckner)
- 17:40-17:50 Questions and discussion
- 17:50-17:55 **Closing remarks** (Alexander Wiebel)
- 17:55

Motivation

<http://tutorials.awmw.org/DirectVolumeInteraction>

Direct Volume Interaction



1388

IEEE TRANSACTIONS ON VISUALIZATION AND COMPUTER GRAPHICS, VOL. 14, NO. 6, NOVEMBER/DECEMBER 2008

Direct Volume Editing

Kai Bürger, Jens Krüger, and Rüdiger Westermann

Abstract—In this work we present basic methodology for interactive volume editing on GPUs, and we demonstrate the use of these methods to achieve a number of different effects. We present fast techniques to modify the appearance and structure of volumetric scalar fields given on Cartesian grids. Similar to 2D circular brushes as used in surface painting we present 3D spherical brushes for intuitive coloring of particular structures in such fields. This paint metaphor is extended to allow the user to change the data itself, and the use of this functionality for interactive structure isolation, hole filling, and artefact removal is demonstrated. Building on previous work in the field we introduce high-resolution selection volumes, which can be seen as a resolution-based focus+context metaphor. By utilizing such volumes we present a novel approach to interactive volume editing at sub-voxel accuracy. Finally, we introduce a fast technique to paste textures onto iso-surfaces in a 3D scalar field. Since the texture resolution is independent of the volume resolution, this technique allows structure-aligned textures containing appearance properties or textual information to be used for volume augmentation and annotation.

Index Terms—Volume editing, GPU, painting, carving, annotations.

1 INTRODUCTION

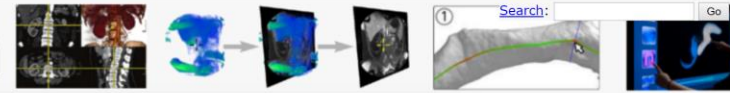
Interactive visual exploration of volumetric scalar fields is required in many different areas ranging from medicine and engineering to physics and biology. To support the exploration task, volume rendering techniques have been developed to a high degree of sophistication over the last decade. Today, direct volume rendering of data sets as

methodology, if designed in a generic way without the restriction to a particular application, then has the potential to be used in a number of different scenarios. In particular, to support the editing process and to avoid putting the burden completely on the user, optional constraints can be integrated into these methods.

Motivation

<http://tutorials.awmw.org/DirectVolumeInteraction>

Direct Volume Interaction



1388

IEEE TRANSACTIONS ON

Ka

Abstract—In this work we present b methods to achieve a number of diffe scalar fields given on Cartesian grids for intuitive coloring of particular stru itself, and the use of this functionalit on previous work in the field we intro metaphor. By utilizing such volumes introduce a fast technique to paste te volume resolution, this technique allo for volume augmentation and annota

Index Terms—Volume editing, GPU,

1 INTRODUCTION

Interactive visual exploration of volumetr in many different areas ranging from me physics and biology. To support the explor ing techniques have been developed to a hi over the last decade. Today, direct volum

Direct-Manipulation Visualization of Deep Networks

Daniel Smilkov
Google, Inc.
5 Cambridge Center,
Cambridge MA, 02142
smilkov@google.com

Shan Carter
Google, Inc.
1600 Amphitheater Parkway,
Mountain View CA, 94043
shancarter@google.com

D. Sculley
Google, Inc.
5 Cambridge Center,
Cambridge MA, 02142
dsculley@google.com

Fernanda B. Viégas
Google, Inc.
5 Cambridge Center,
Cambridge MA, 02142
viegas@google.com

Martin Wattenberg
Google, Inc.
5 Cambridge Center,
Cambridge MA, 02142
wattenberg@google.com

ABSTRACT

The recent successes of deep learning have led to a wave of interest from non-experts. Gaining an understanding of this technology, however, is difficult. While the theory is im-

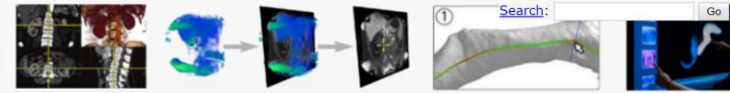
Recently, several impressive systems have appeared that do exactly this. Olah's elegant interactive online essays [5] let a viewer watch the training of a simple classifier, providing a multiple perspectives on how a network learns a transformation of space. Karpathy created a Javascript library [4]

2 Aug 2017

Motivation

<http://tutorials.awmw.org/DirectVolumeInteraction>

Direct Volume Interaction



1388

IEEE TRANSACTIONS ON

Indirect Multi-Touch Interaction for Brushing in Parallel Coordinates

Robert Kosara

UNC Charlotte, USA

ABSTRACT

Interaction in visualization is often complicated and tedious. Brushing data in a visualization such as parallel coordinates is a central part of the data analysis process, and sets visualization apart from static charts. Modifying a brush, or combining it with another one, usually requires a lot of effort and mode switches, though, slowing down interaction and even discouraging more complex questions.

We propose the use of multi-touch interaction to provide fast and convenient interaction with parallel coordinates. By using a multi-touch trackpad rather than the screen directly, the user's hands do not obscure the

works

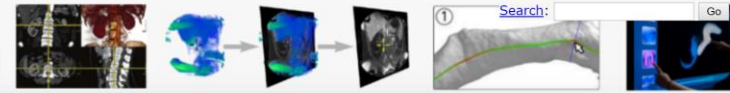
by
C.
Center,
02142
gle.com

ave appeared that do
e online essays [5] let
e classifier, providing
ork learns a transfor-
Javascript library [4]

Motivation

<http://tutorials.awmw.org/DirectVolumeInteraction>

Direct Volume Interaction



1388

IEEE TRANSACTIONS ON VISUALIZATION AND COMPUTER-BASED GRAPHICS

HUMAN-COMPUTER INTERACTION, 1985, Volume 1, pp. 311-338
Copyright © 1985, Lawrence Erlbaum Associates, Inc.

Direct Manipulation Interfaces

**Edwin L. Hutchins, James D. Hollan, and
Donald A. Norman**

University of California, San Diego

Interacting
coordinates
ifying a k
slowing d

We pr
dinates.

1
Inte
in 1
phy
ing
ove

Motivation

<http://tutorials.awmw.org/DirectVolumeInteraction>

Direct manipulation systems offer the satisfying experience of operating on visible objects. The computer becomes transparent, and users can concentrate on their tasks.

Direct Manipulation: A Step Beyond Programming Languages

Ben Shneiderman, University of Maryland

Leibniz sought to make the form of a symbol reflect its content. "In signs," he wrote, "one sees an advantage for discovery that is greatest when they express the exact nature of a thing briefly and, as it were, picture it; then, in-

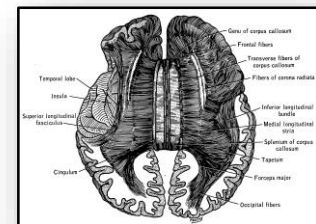
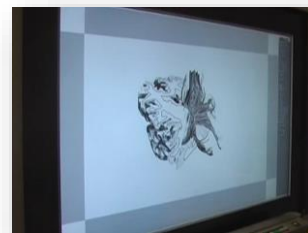
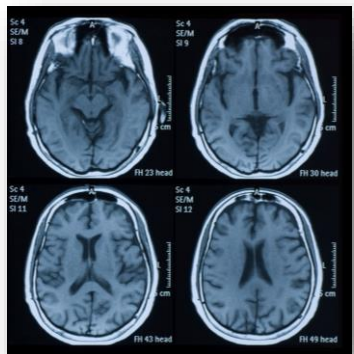
Examples of direct manipulation systems

No single system has all the attributes or design fea-



Questions

- What is “directness” in the context of interactive visualization?
- Is directness a useful notion for better understanding the interplay between visualization and interaction?
- What are the (sub-)dimensions of directness?
- Can we measure it? Can we predict it?



data
space \mathcal{D}

visualization
mapping
 v

visualization
space
 \mathcal{V}

output
mapping
 o

output
space
 \mathcal{O}

user
perception
 u_p

user
space
 \mathcal{U}

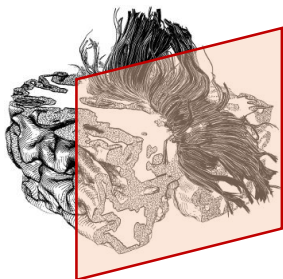
interaction
mapping
 i

interaction
space
 \mathcal{I}

manipulation
mapping
 m

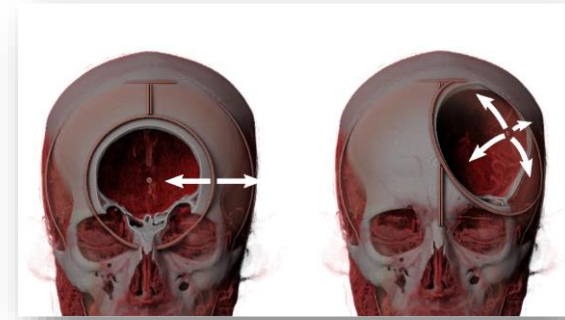
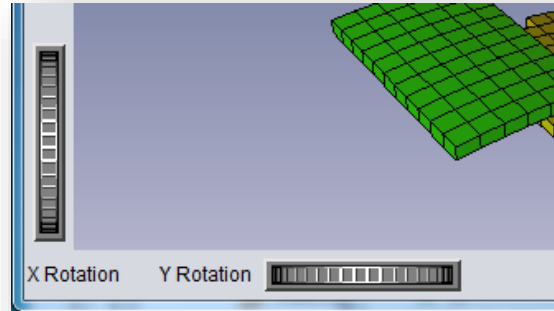
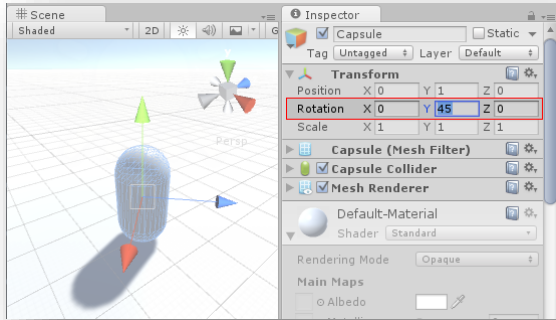
manipulation
space
 \mathcal{M}

user
action
 u_a

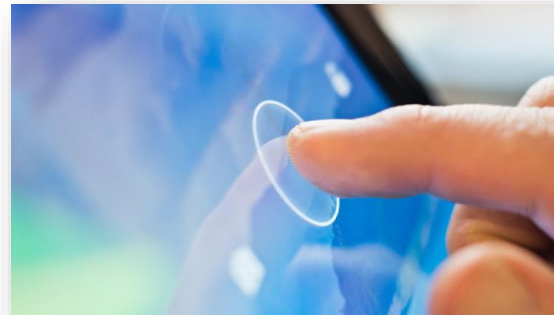


Dimensions of Directness

- Visualization-interaction (vi) directness

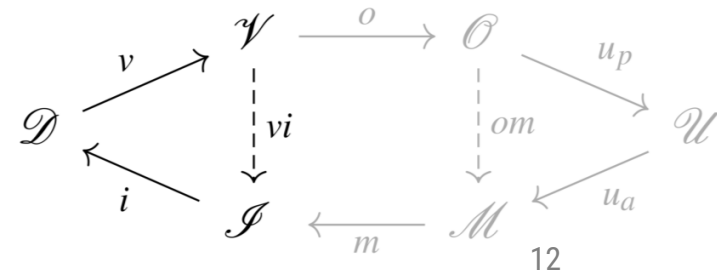
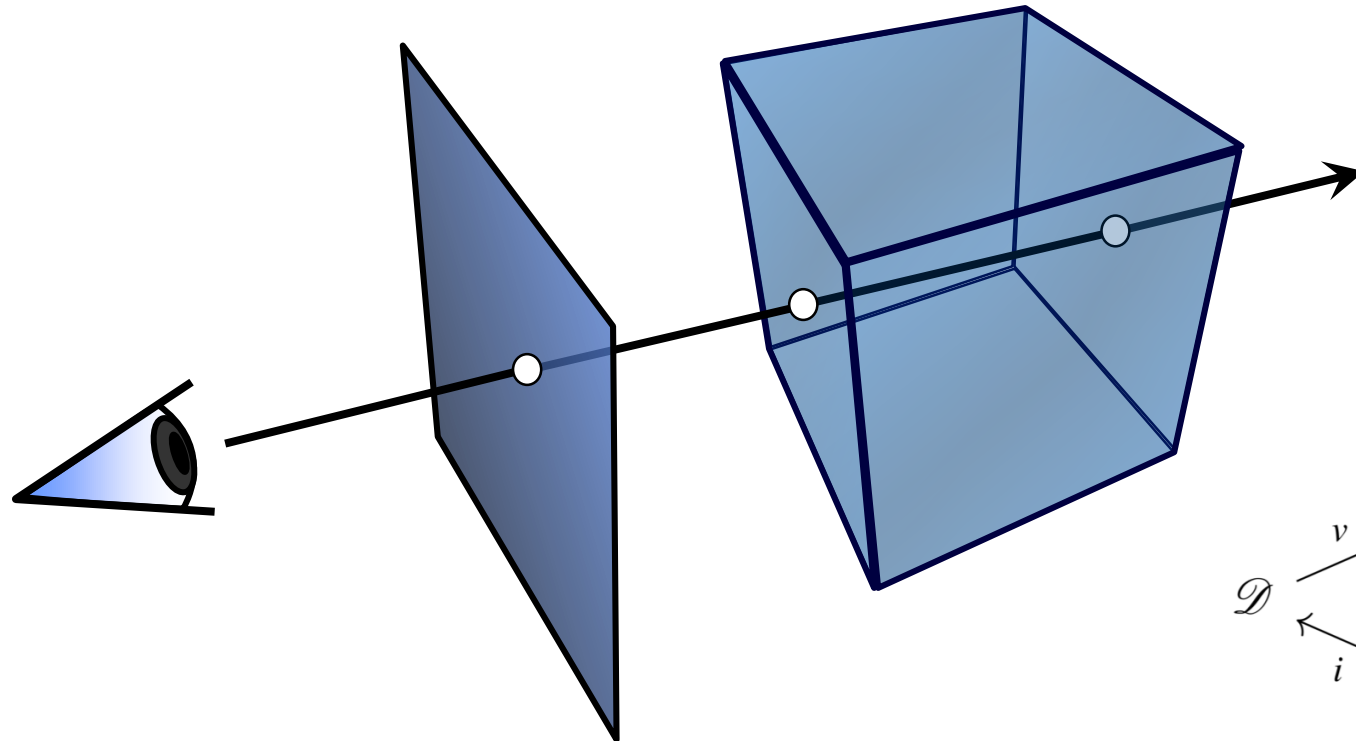


- Output-manipulation (om) directness



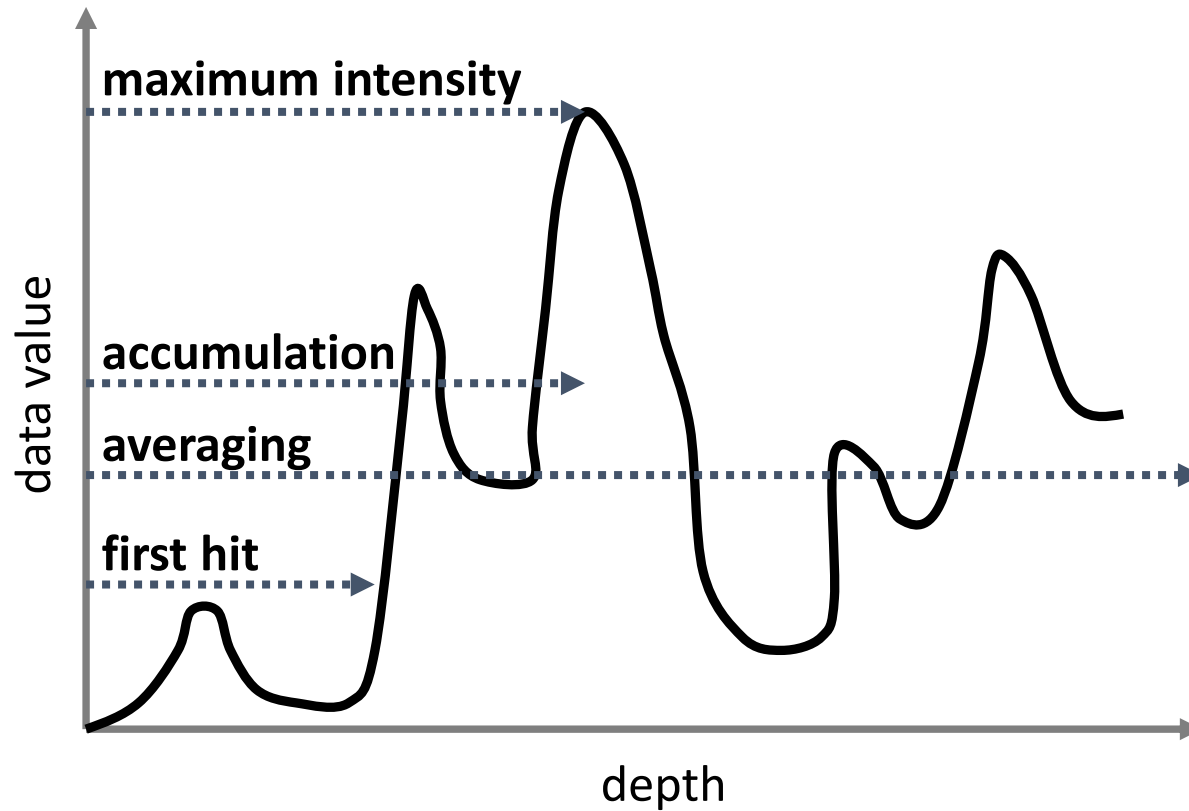
Example: Point Picking in VolVis

- Reconstruct 3D position from picked point in 2D image
 - We encounter many data values along a viewing ray
 - Compositing function defines how data values contribute to a pixel



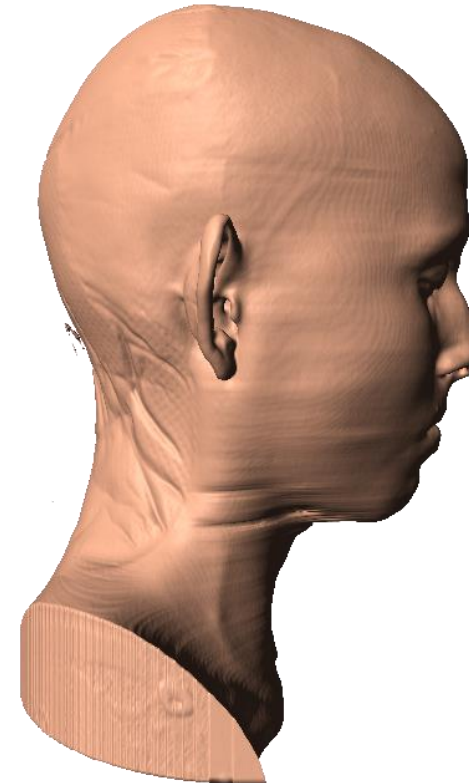
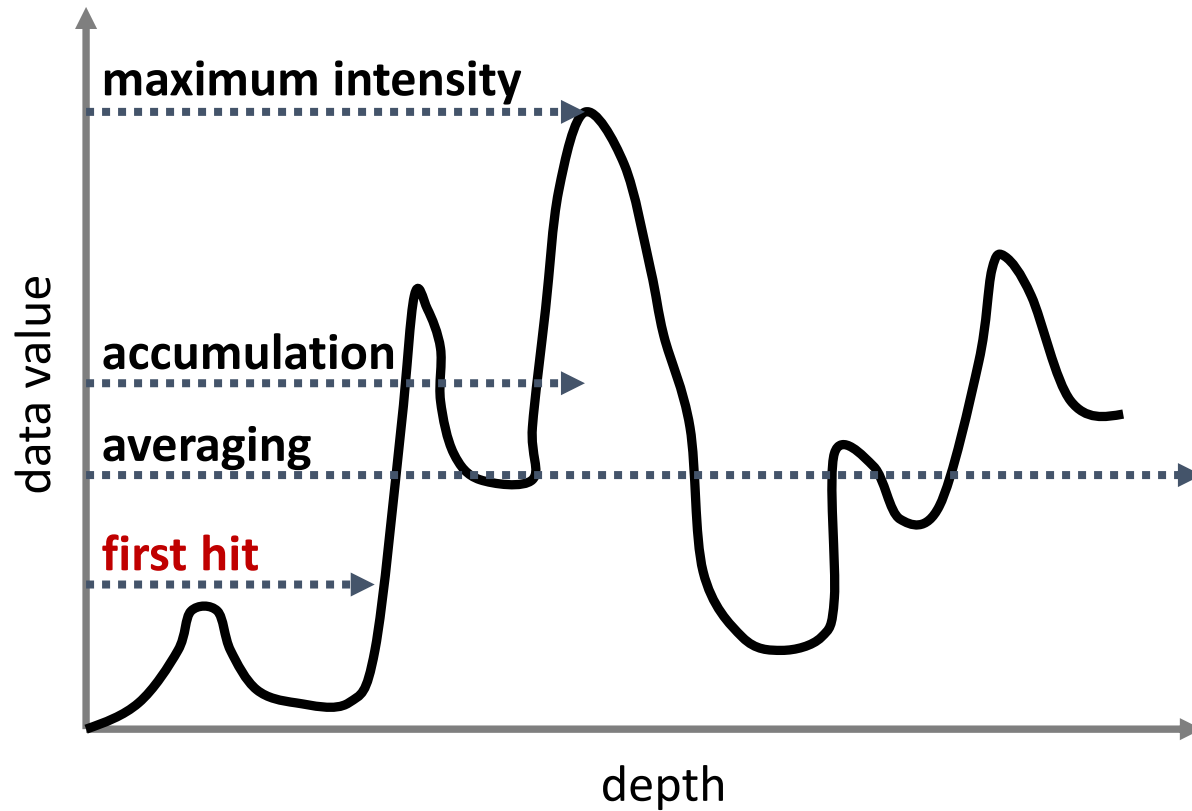
Types of Compositing

intensity profile along a viewing ray



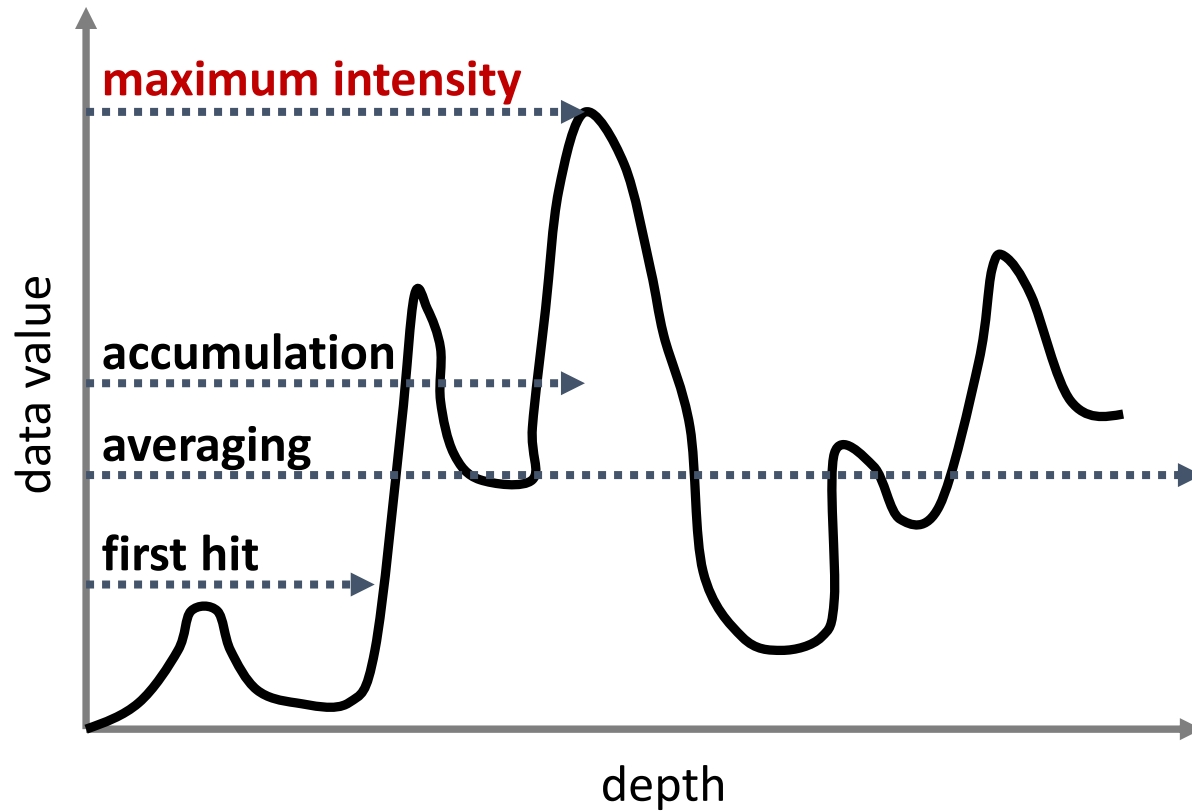
Types of Compositing

intensity profile along a viewing ray



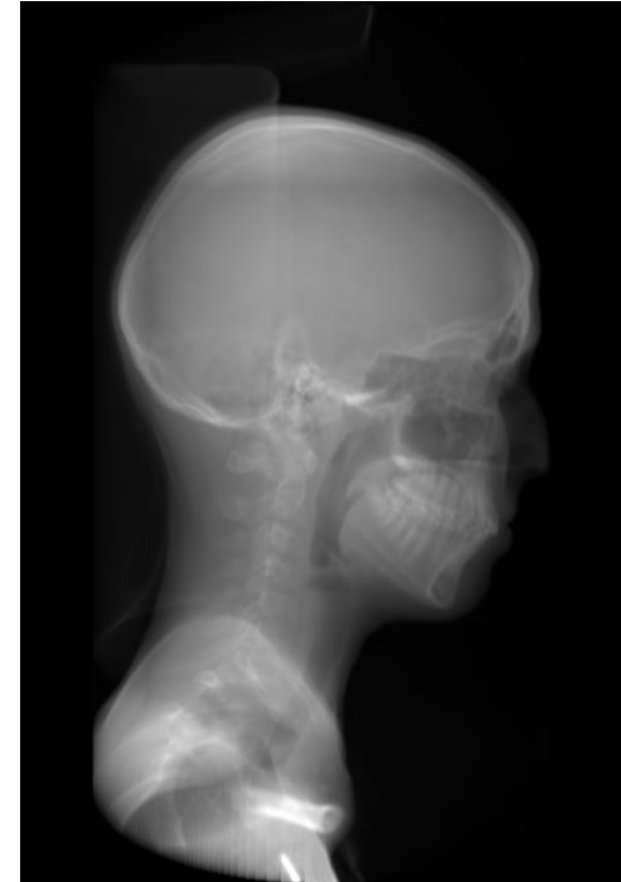
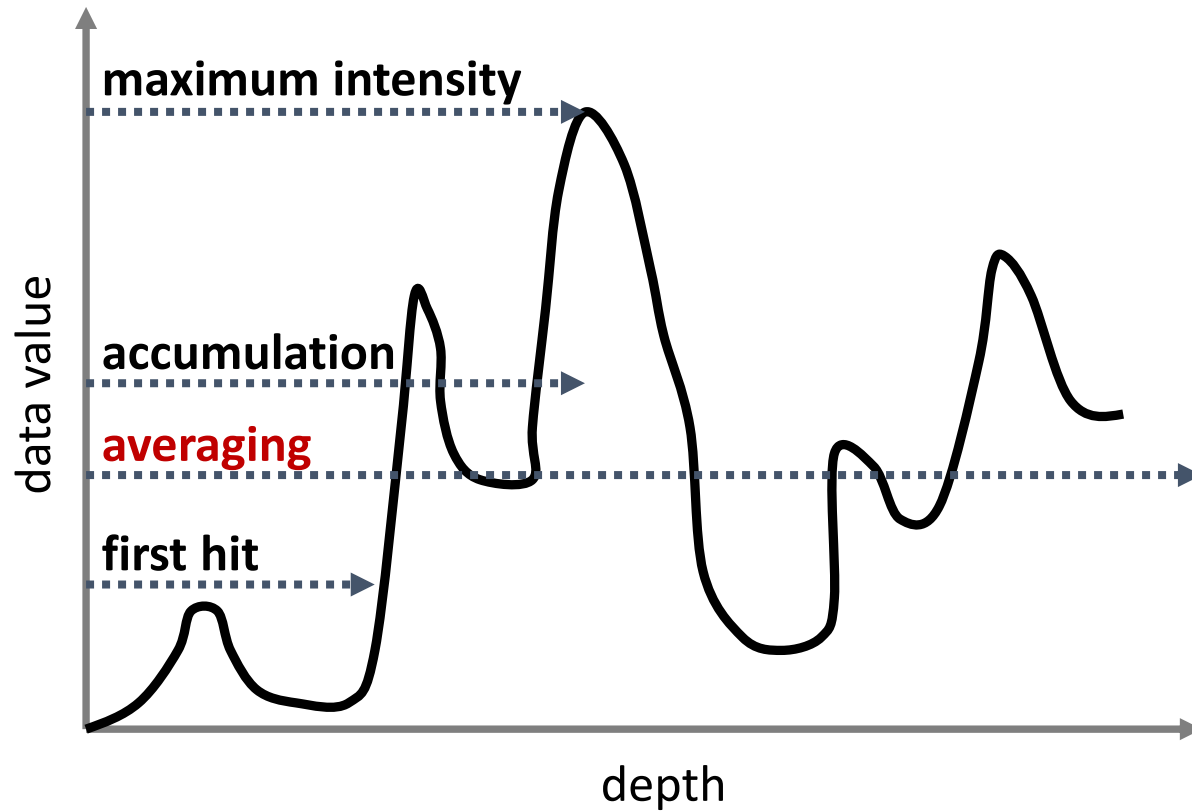
Types of Compositing

intensity profile along a viewing ray



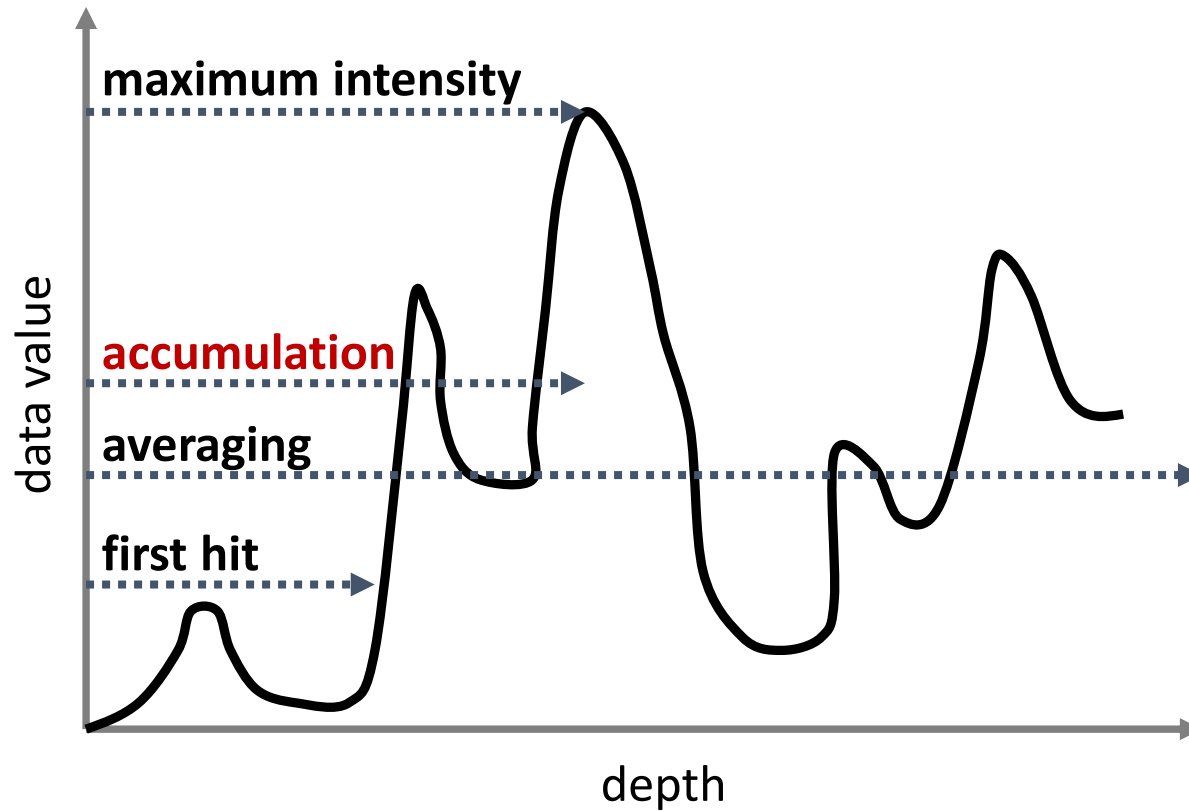
Types of Compositing

intensity profile along a viewing ray



Types of Compositing

intensity profile along a viewing ray



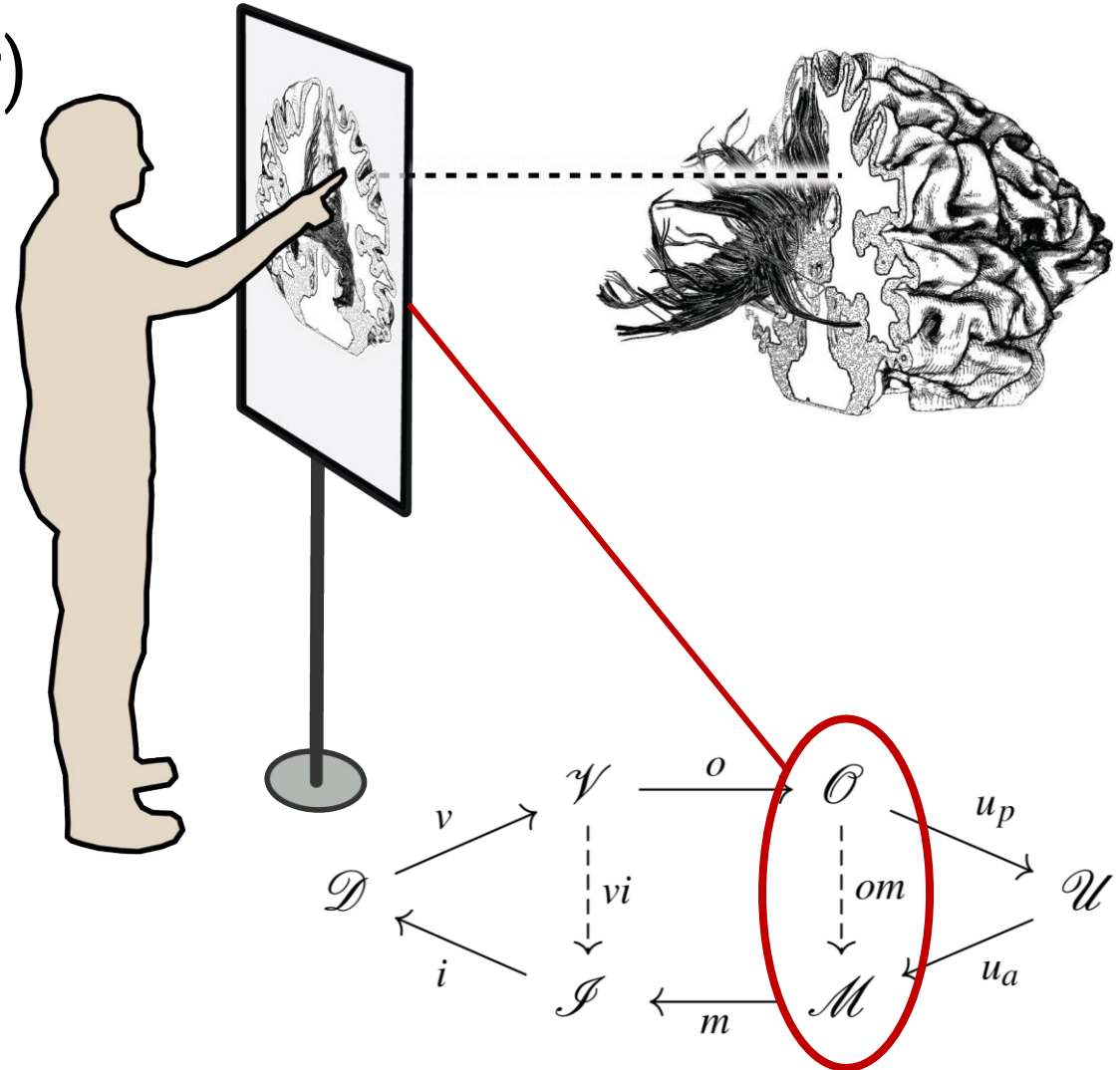
VolVis Point Picking Directness

- Illustrates limits in achievable vi-directness when dealing with 3D data
- Higher vi-directness possible, if compositing function can be inverted
 - **First hit, maximum intensity:** can unambiguously reconstruct 3D position from 2D pixel location
 - **Averaging:** all samples contribute equally to the pixel, reconstruction not possible
 - **Accumulation:** may be able to heuristically reconstruct “close” 3D position in some cases (interaction mapping is a *quasi-inverse* of the visualization mapping)

Direct Input for 3D Data?

- Manipulation space: 2 DOF (1 finger)
- Interaction space:
 - 3 DOF for position
 - 3 DOF for orientation
 - 1–3 DOF for scale
 - n DOF for additional parameters
- All per object/element
- typically control of only 4 DOF simultaneously (4–5 max.)*

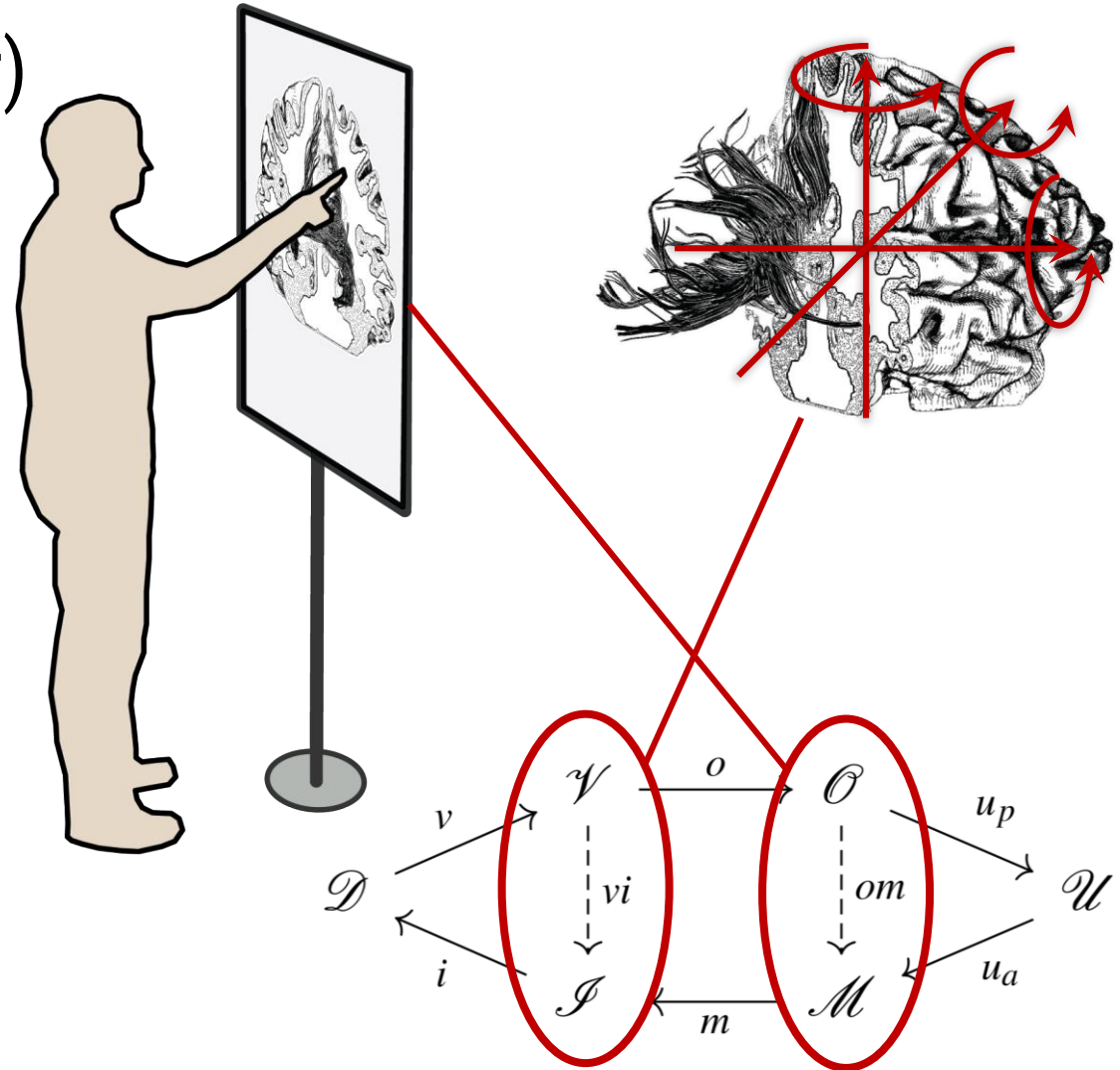
** some scientific evidence for this limit*



Direct Input for 3D Data?

- Manipulation space: 2 DOF (1 finger)
- Interaction space:
 - 3 DOF for position
 - 3 DOF for orientation
 - 1–3 DOF for scale
 - n DOF for additional parameters
- All per object/element
- typically control of only 4 DOF simultaneously (4–5 max.)*

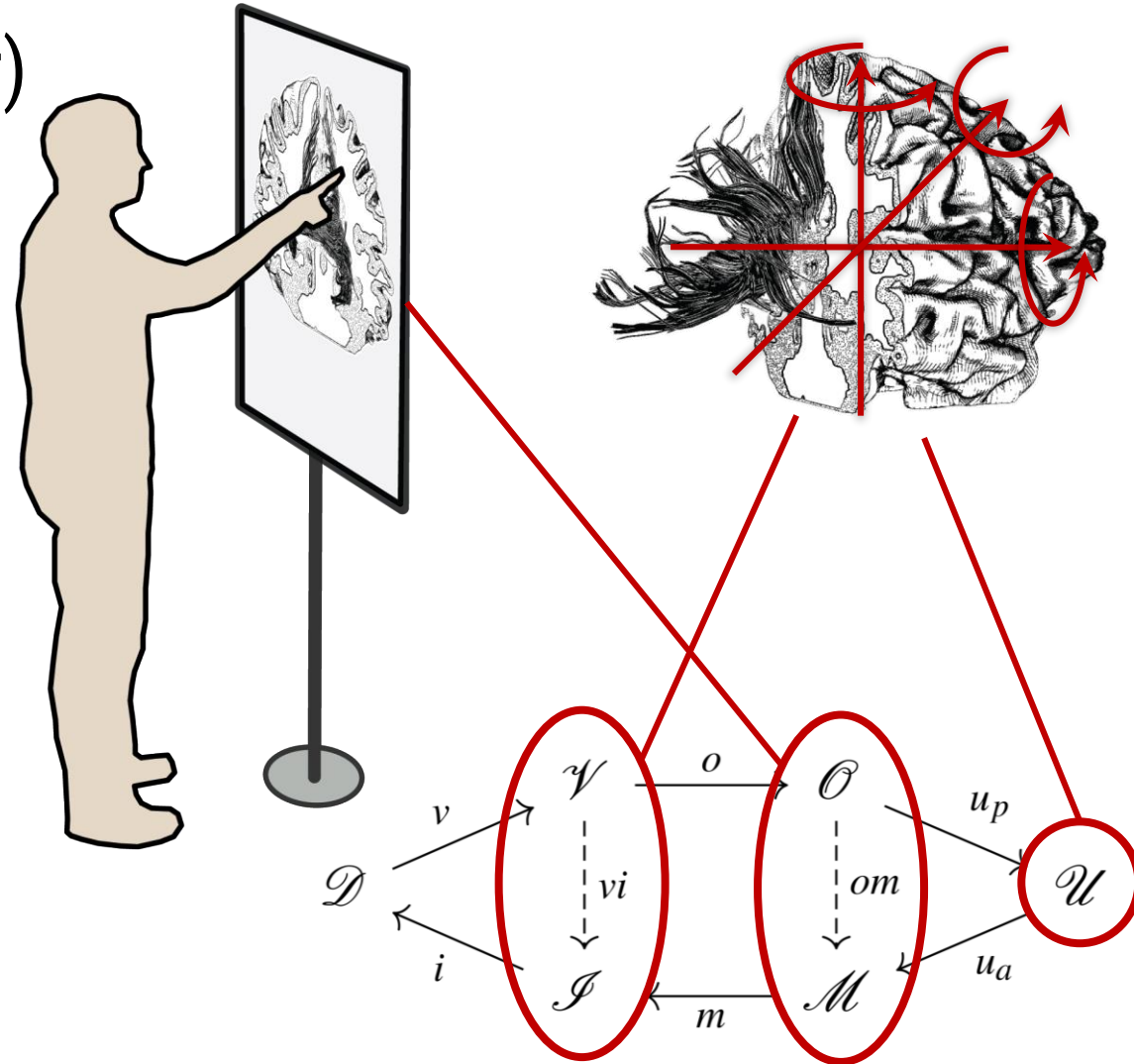
** some scientific evidence for this limit*



Direct Input for 3D Data?

- Manipulation space: 2 DOF (1 finger)
- Interaction space:
 - 3 DOF for position
 - 3 DOF for orientation
 - 1–3 DOF for scale
 - n DOF for additional parameters
- All per object/element
- typically control of only 4 DOF simultaneously (4–5 max.)*

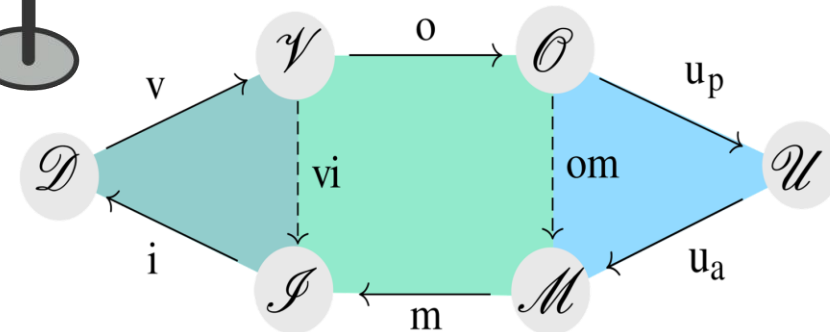
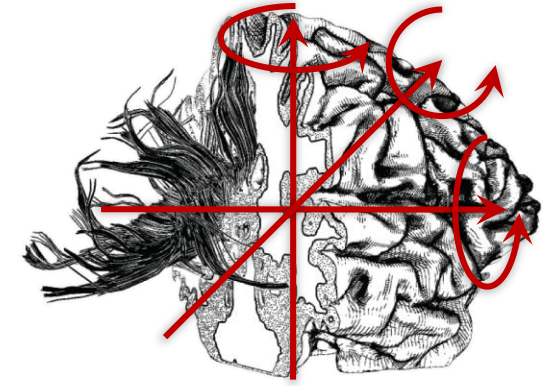
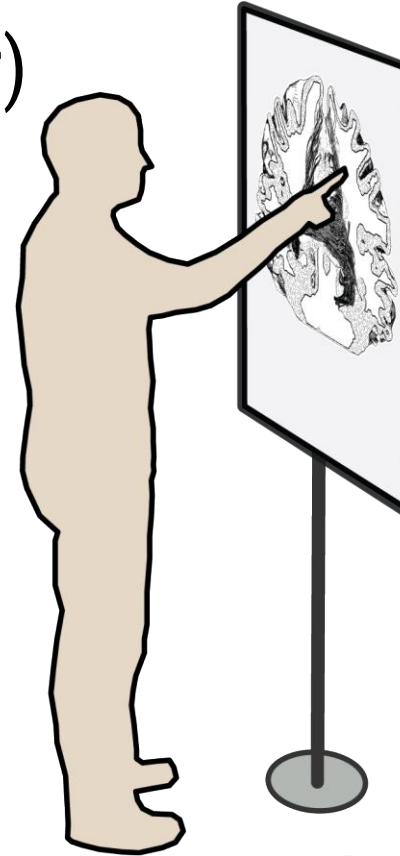
** some scientific evidence for this limit*



Direct Input for 3D Data?

- Manipulation space: 2 DOF (1 finger)
- Interaction space:
 - 3 DOF for position
 - 3 DOF for orientation
 - 1–3 DOF for scale
 - n DOF for additional parameters
- All per object/element
- typically control of only 4 DOF simultaneously (4–5 max.)*

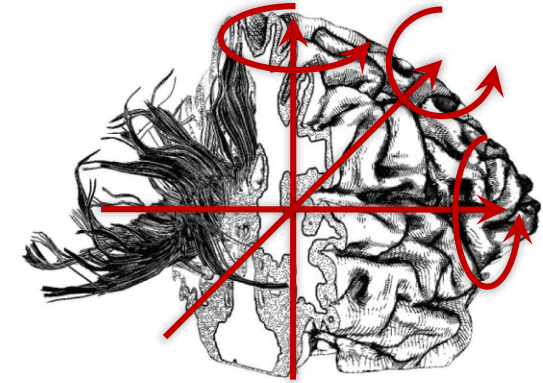
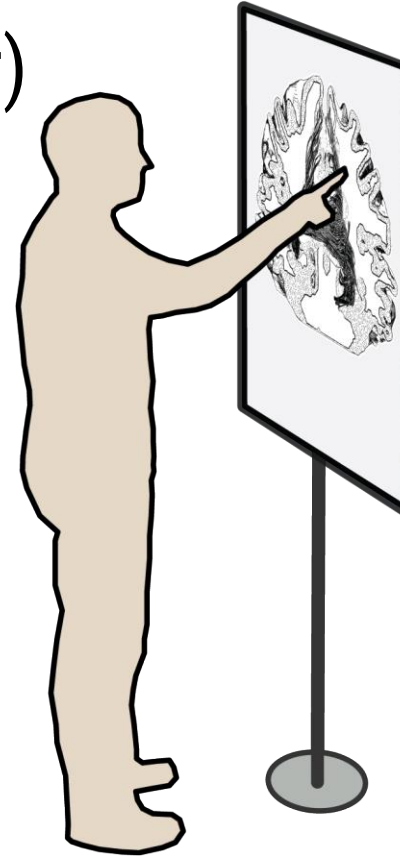
** some scientific evidence for this limit*



Direct Input for 3D Data?

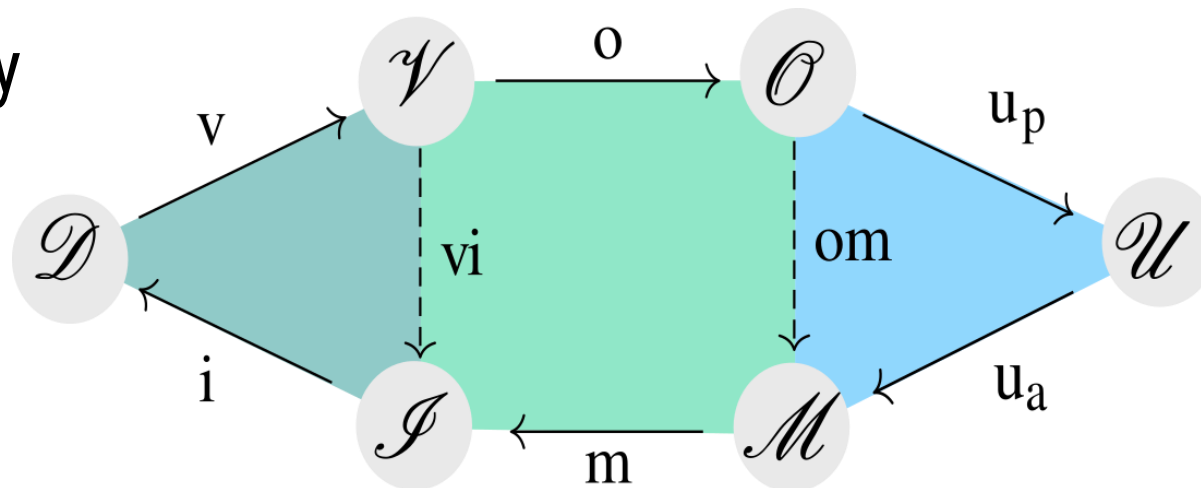
- Manipulation space: 2 DOF (1 finger)
- Interaction space:
 - 3 DOF for position
 - 3 DOF for orientation
 - 1–3 DOF for scale
 - n DOF for additional parameters
- All per object/element
- typically control of only 4 DOF simultaneously (4–5 max.)*

** some scientific evidence for this limit*



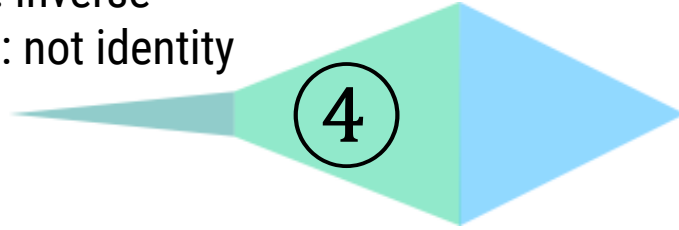
Classification of Directness by Mapping Type

- Visualization-interaction directness: 3 vi-mapping types
 - Inverse
 - Quasi-inverse
 - Non-Inverse
- Output-manipulation directness: 2 om-mapping types
 - Identity
 - Not identity



6 Classes (3 vi \times 2 om)

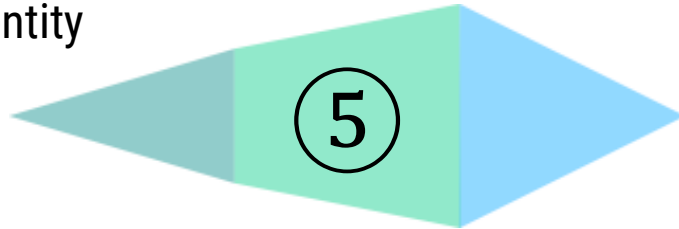
v, i : inverse
om : not identity



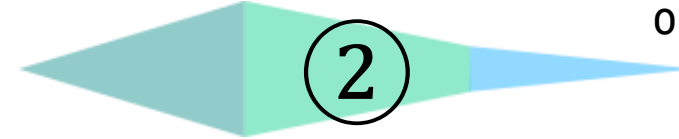
v, i : inverse
om : identity



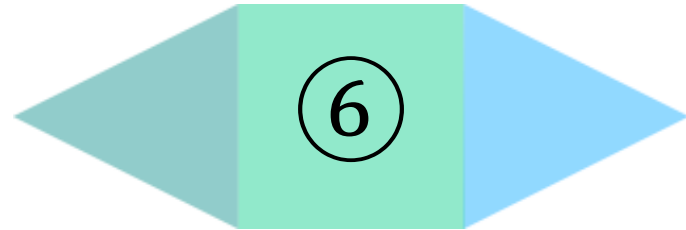
v, i : quasi-inverse
om : not identity



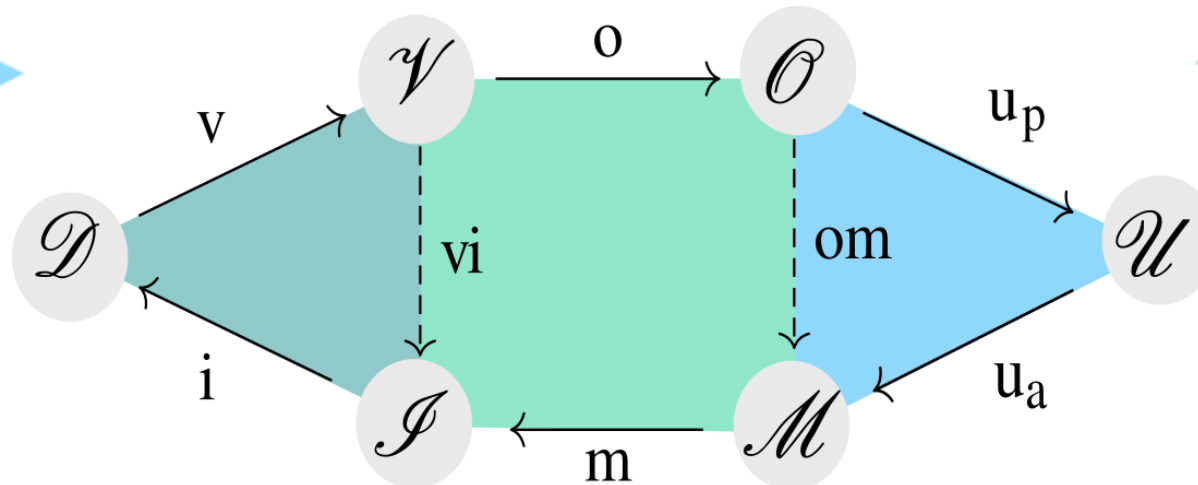
v, i : quasi-inverse
om : identity



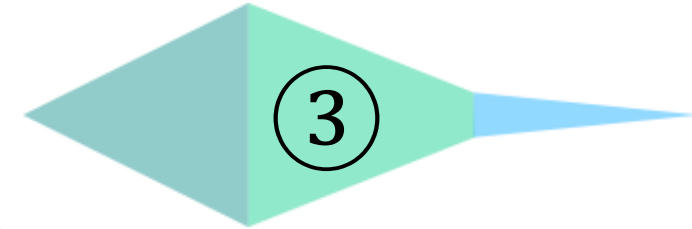
6



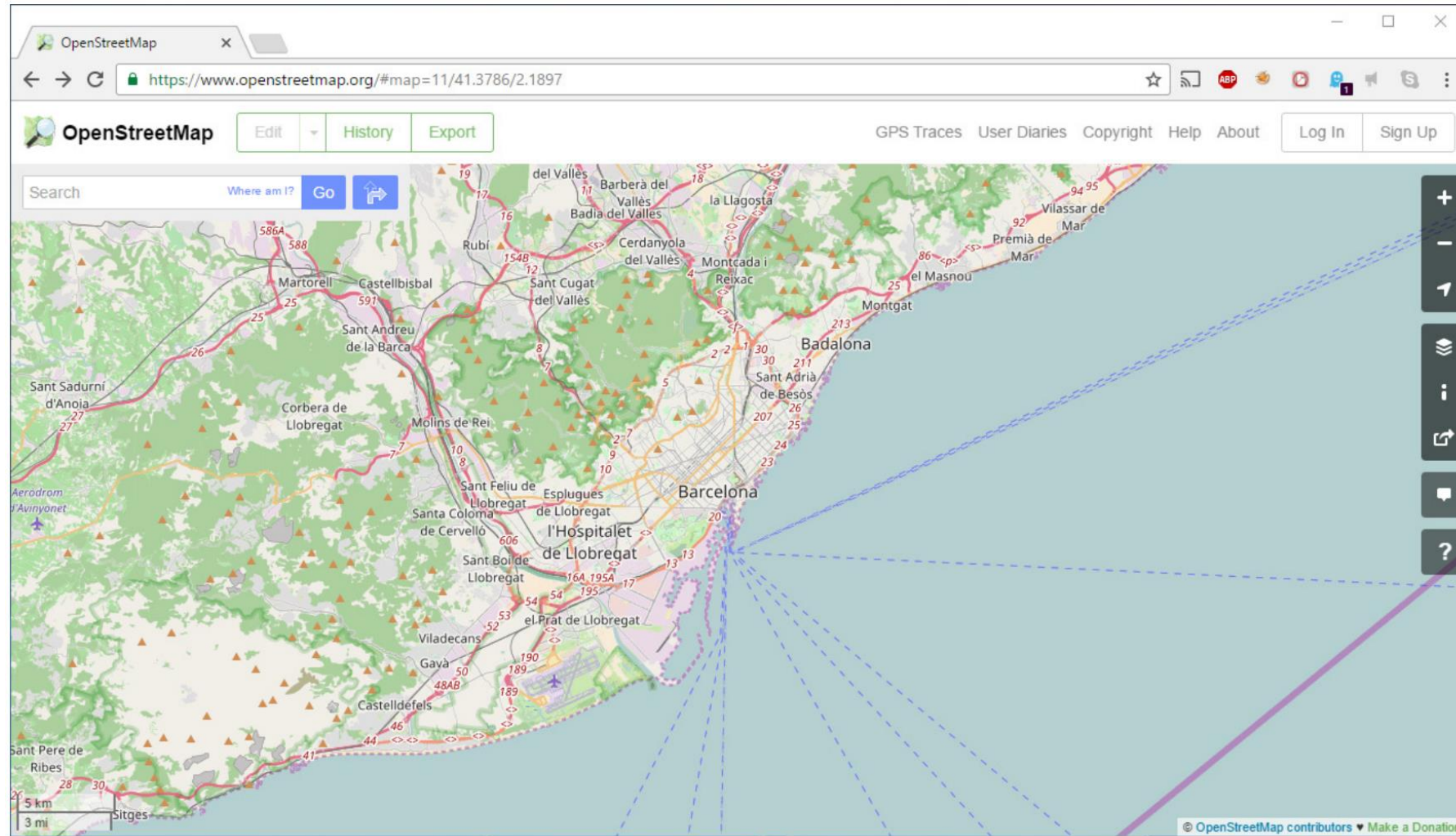
v, i : non-inverse
om : not identity



v, i : non-inverse
om : identity

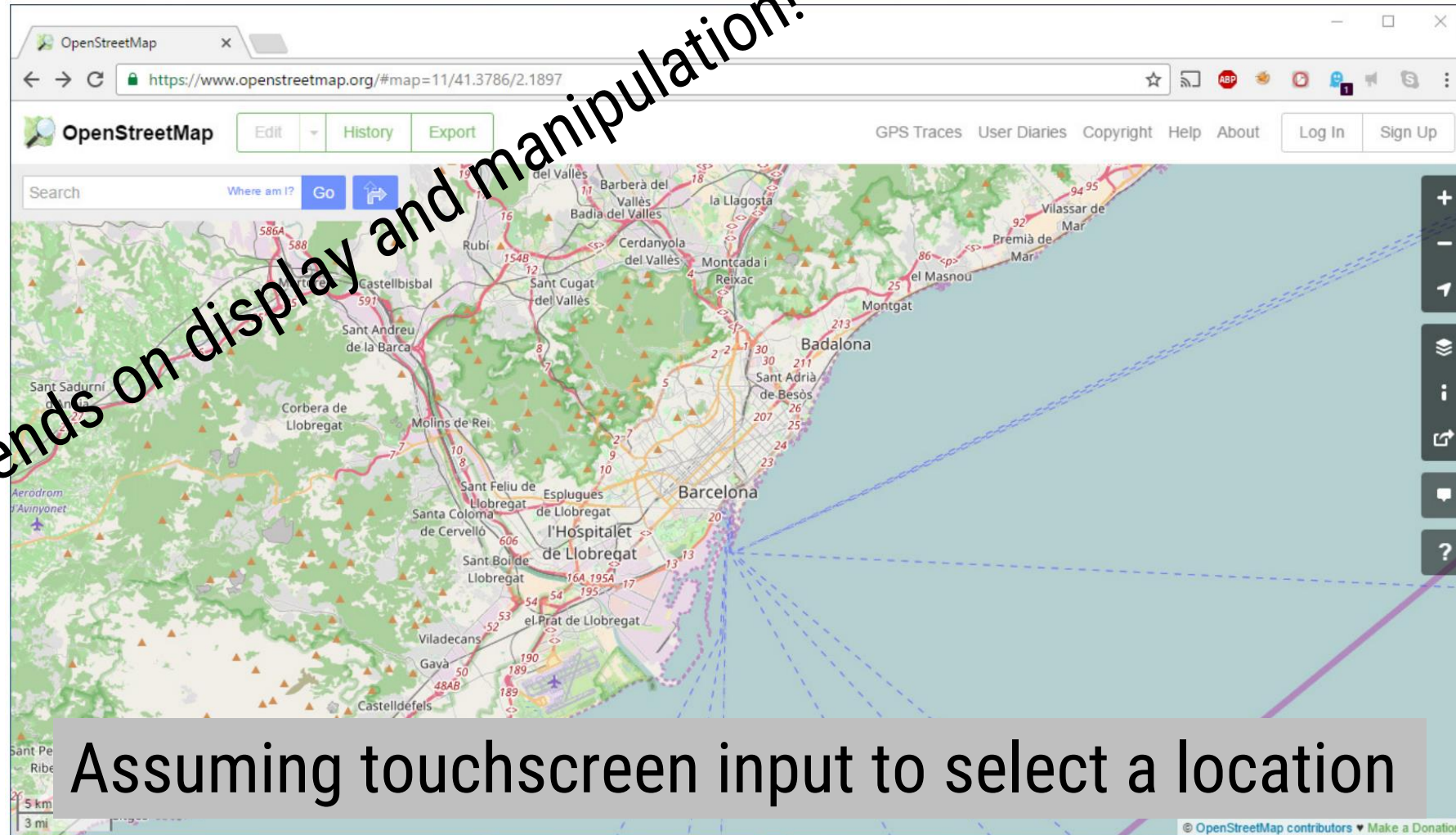


Example: Which Class?

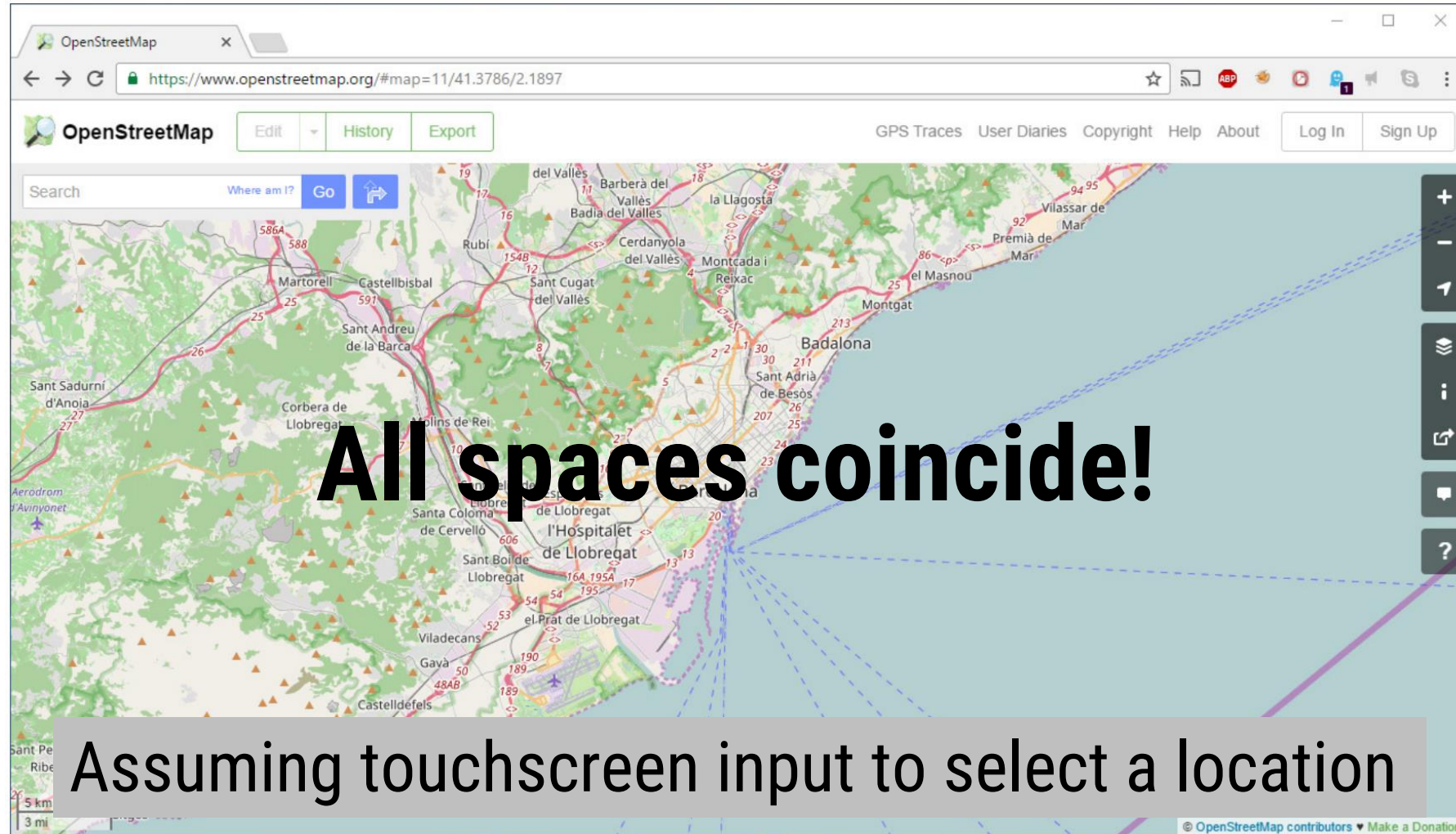


Example: Which Class?

Depends on display and manipulation!



Example: Class 1



Example: Which Class?

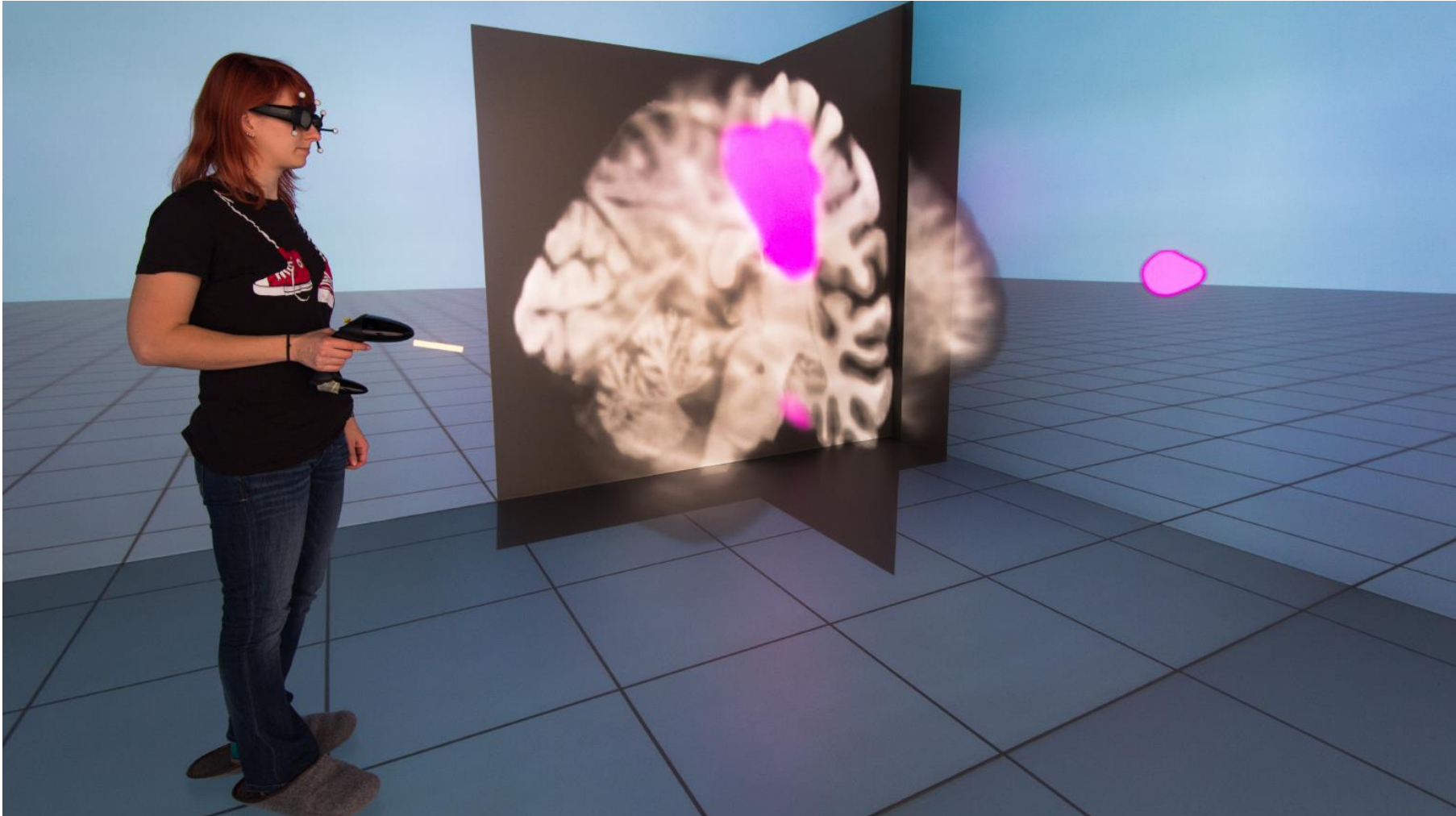


Image courtesy of and © Claudia Hänel and Bernd Hentschel, used with permission.

Example: Class 1

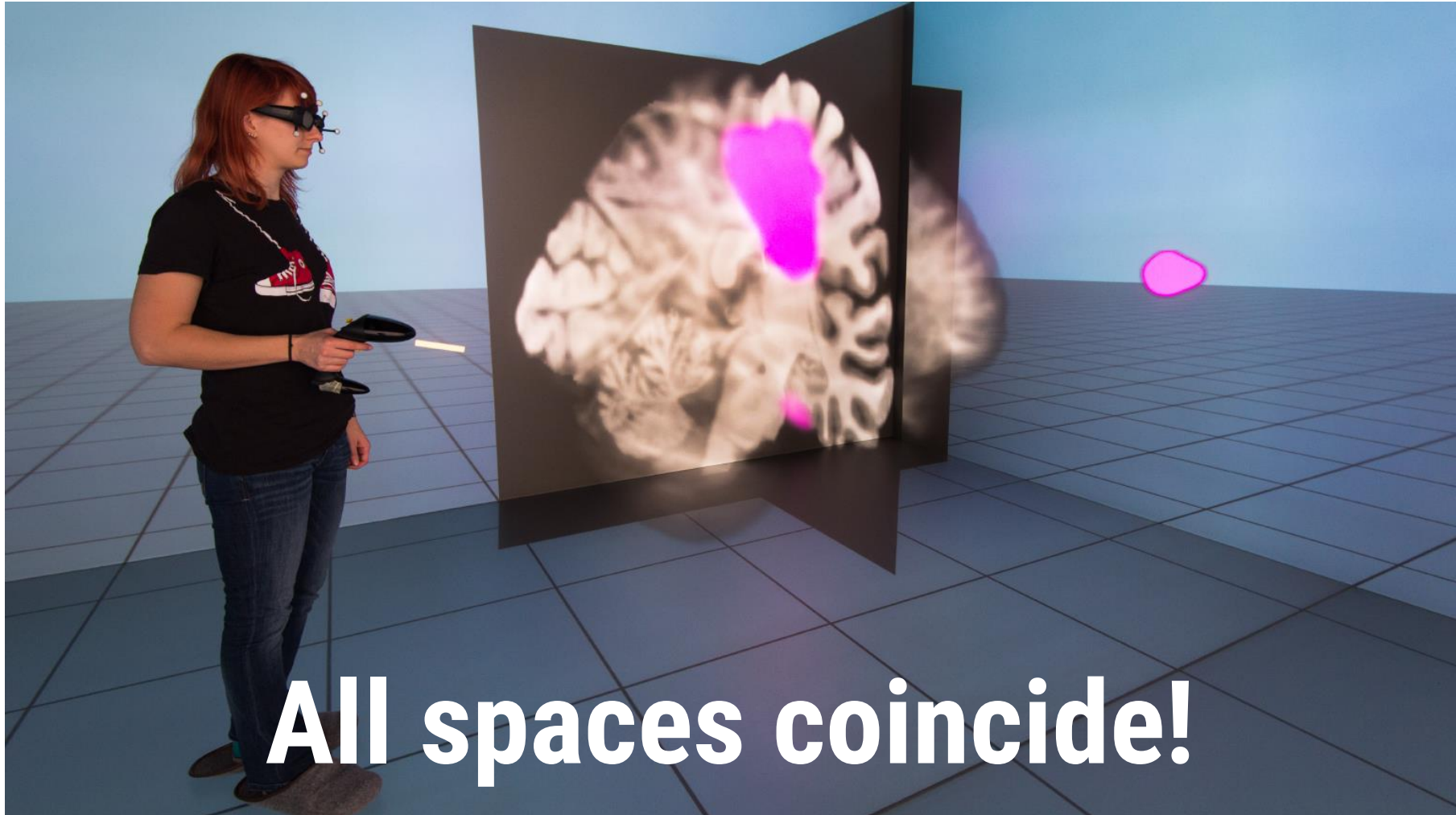
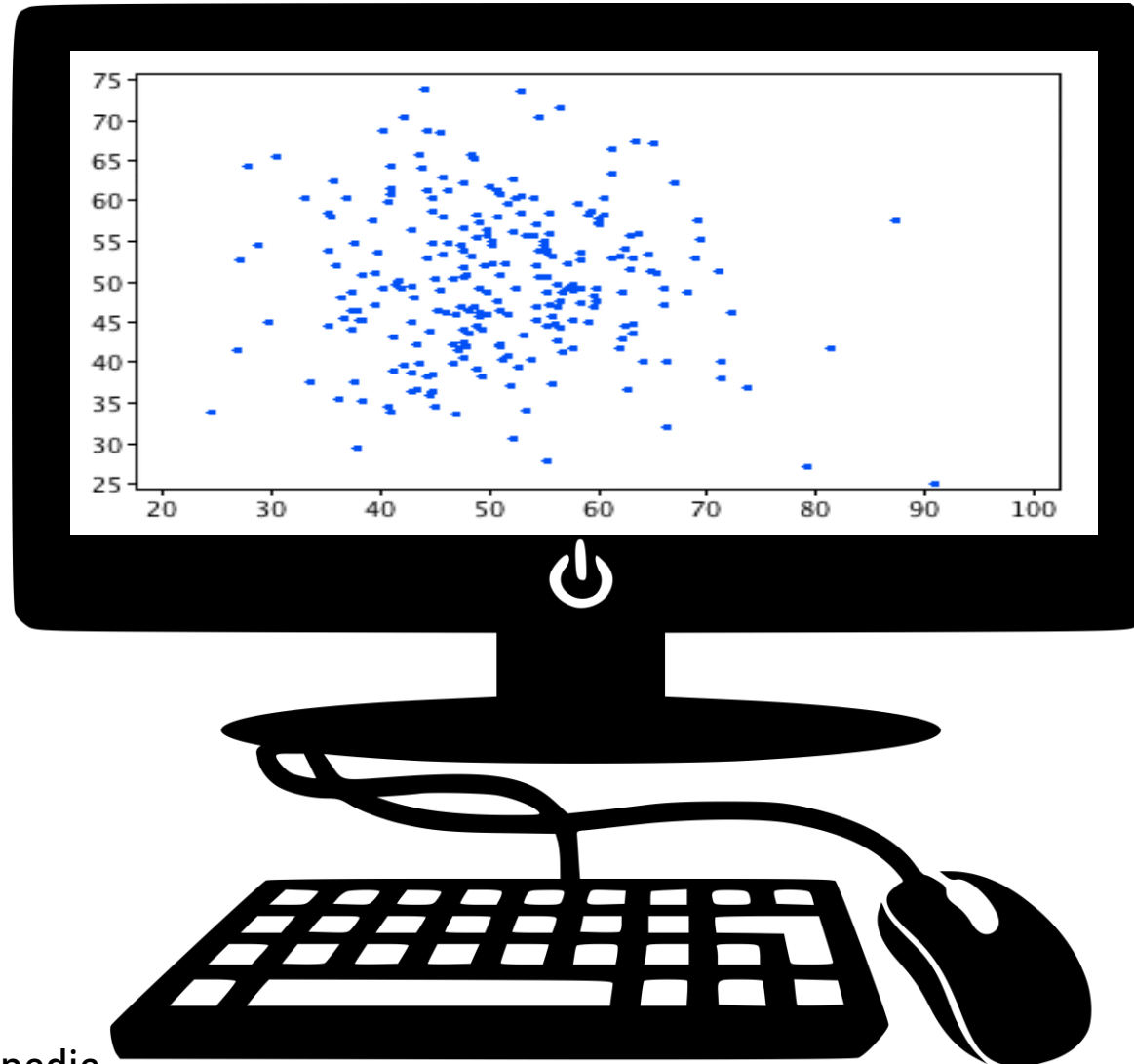
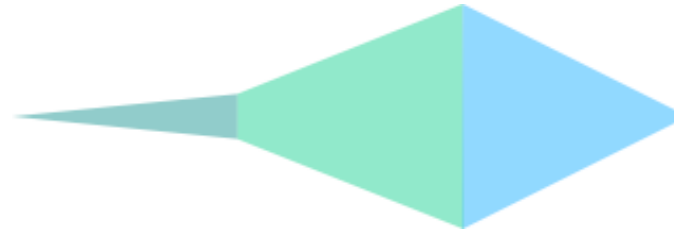


Image courtesy of and © Claudia Hänel and Bernd Hentschel, used with permission.

Example: Class 4



Towards Measuring vi-Indirectness

$$\Delta_{v,i} = \int \underbrace{I(x)}_{\text{importance/relevance of a data location } x; \text{ models user tasks}} |x - i(vi(v(x)))| dx$$

See the **paper** for a **detailed example** where we actually **implemented** the measure

Conclusion

Descriptive usage

- Term directness precisely defined
- More Characteristics
- Captures more aspects of directness

Evaluative usage

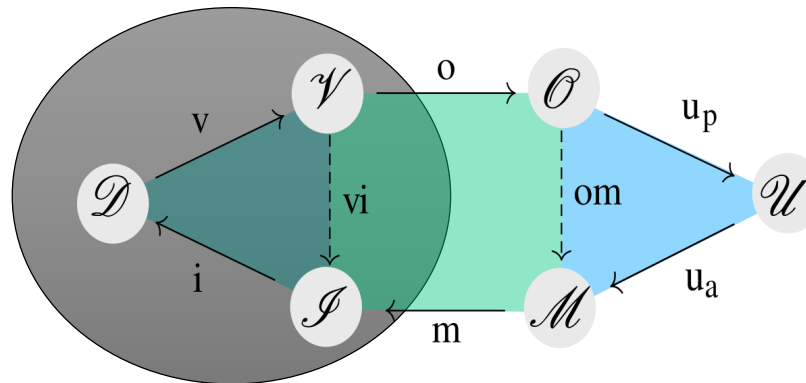
- Classify or even measure directness of existing techniques
- Relate directness to efficiency

Vision:

- **Generative usage**
- Automatically suggest appropriate interaction

Final Notes

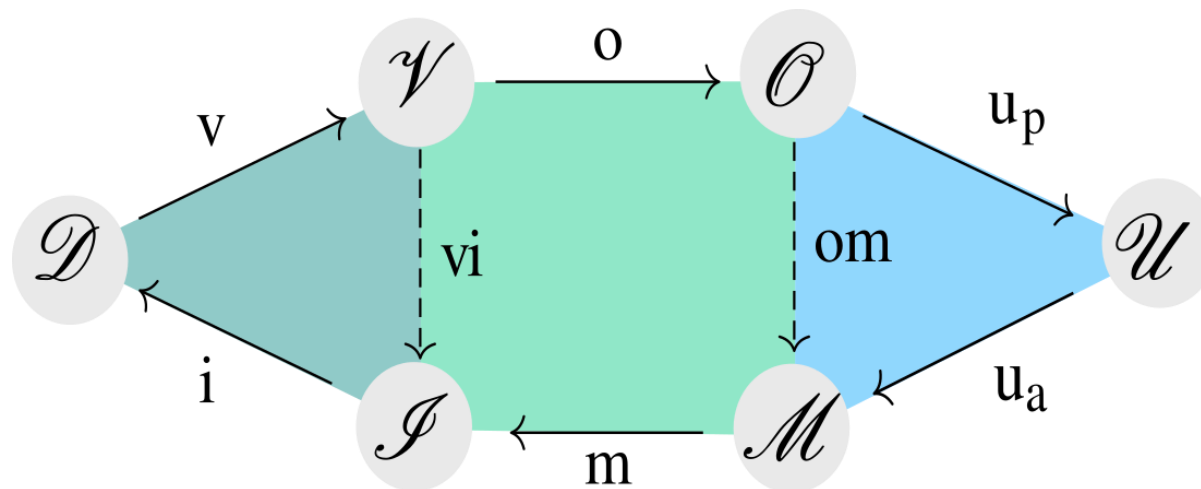
- Often *direct* is interpreted as „better“ than *indirect/less direct*.
 - **This is definitely not always the case!**
 - For certain cases less direct might be advantageous
 - More flexible
 - Faster
- Spatial in the title does not mean spatial data
 - **Abstract data** changes only left part of model



A Model of Spatial Directness in Interactive Visualization

Stefan Bruckner, Tobias Isenberg, Timo Ropinski, Alexander Wiebel

Questions?



We are very grateful for the reviewers' very helpful and constructive feedback!