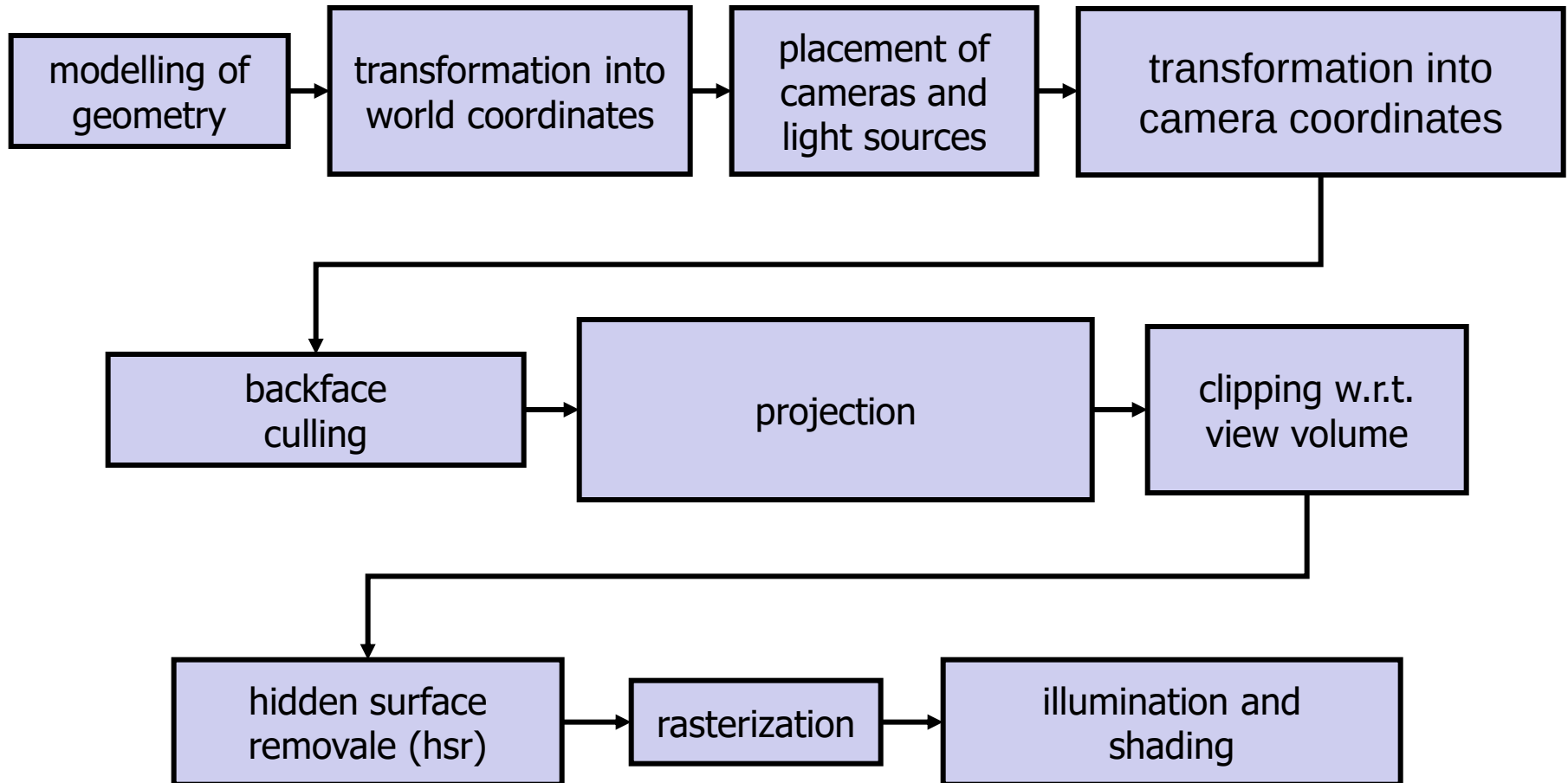


Computer Graphics

Hidden Surface Removal

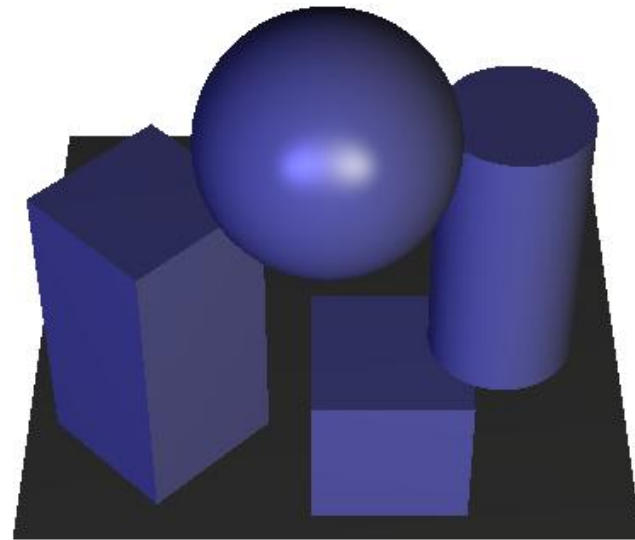
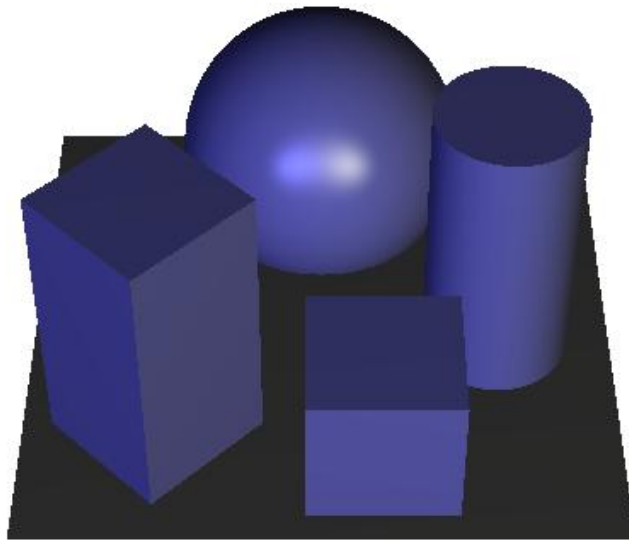
Rendering Pipeline



Hidden Surface Removal

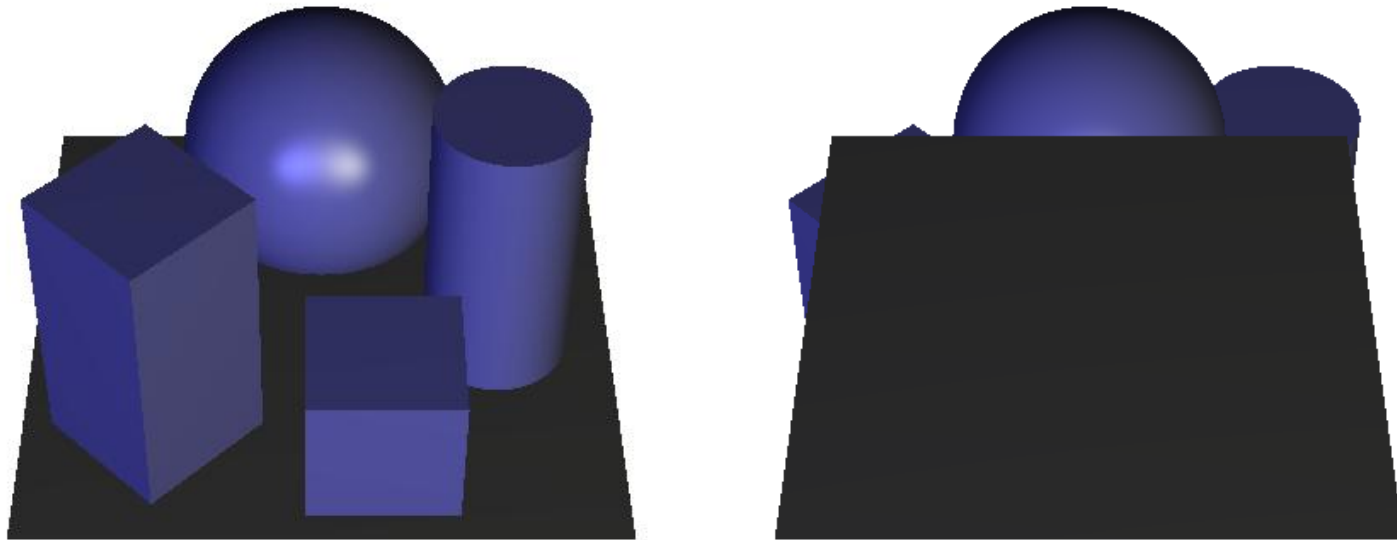
Hidden Surface Removal: Motivation

- goals:
 - model parts independently processed
 - at the same time: show front parts only
 - avoid unnecessary processing



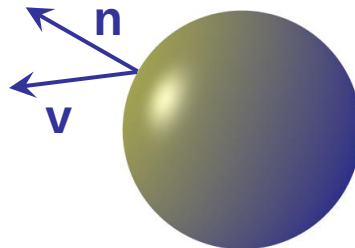
Hidden Surface Removal: Motivation

- goals:
 - model parts independently processed
 - at the same time: show front parts only
 - avoid unnecessary processing



Back Face Culling

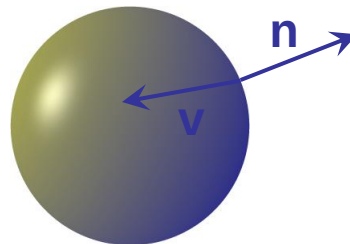
- back faces (usually) not visible
- remove these: reduction of computation
- removal early in the pipeline
- reduction of polygon count by approx. $\frac{1}{2}$ of the total polygon number
- computation: compare dot product of surface normal with view direction with 0



$$n \cdot v > 0$$

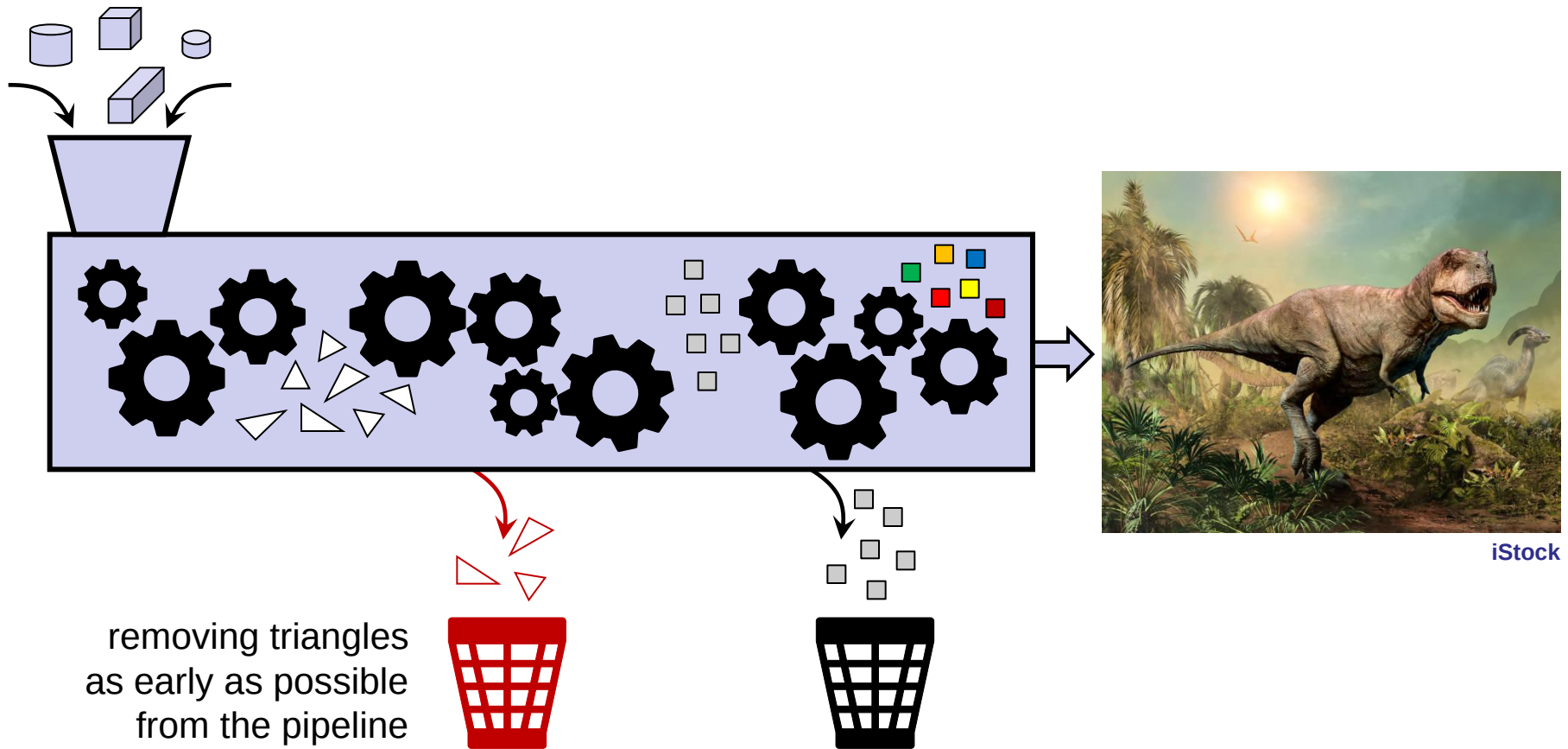
Back Face Culling

- back faces (usually) not visible
- remove these: reduction of computation
- removal early in the pipeline
- reduction of polygon count by approx. $\frac{1}{2}$ of the total polygon number
- computation: compare dot product of surface normal with view direction with 0



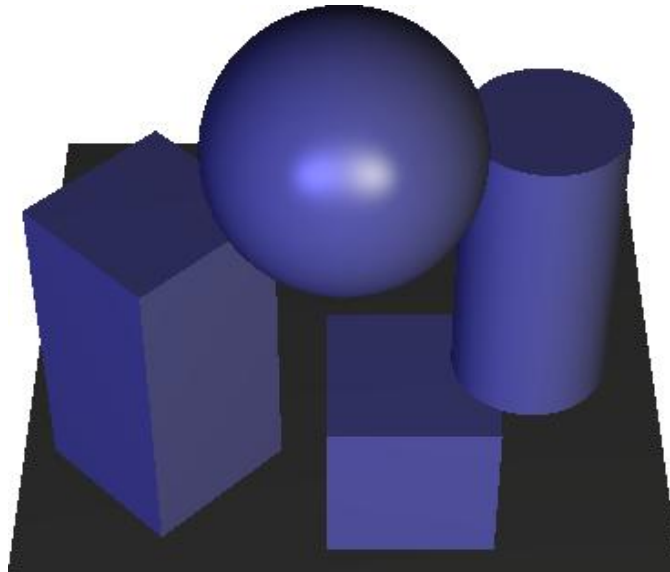
$$\mathbf{n} \cdot \mathbf{v} < 0$$

Back Face Culling: Early Removal



Back Face Culling

- back face culling as HSR technique?
 - (usually) not sufficient due to partial overlaps of several objects in the scene
 - would work reliably only if no overlaps occur
 - e.g., if only one convex object is shown

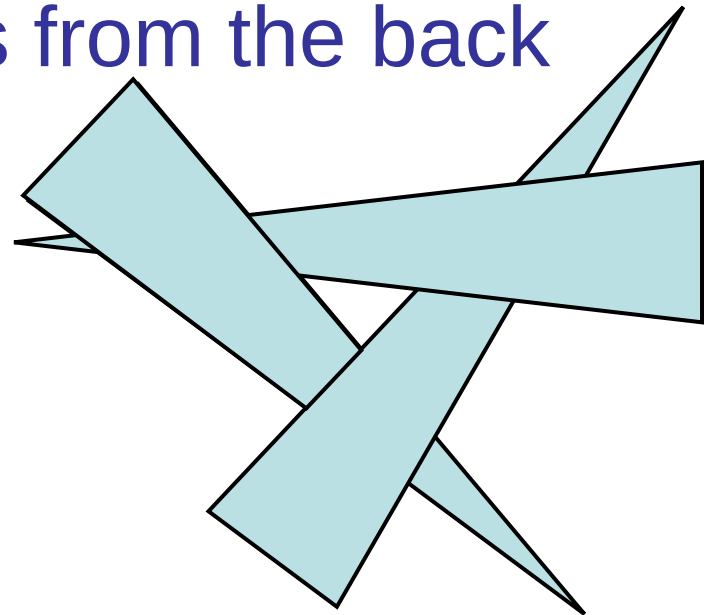


Back Face Culling

- back face culling as HSR technique?
 - (usually) not sufficient due to partial overlaps of several objects in the scene
 - would work reliably only if no overlaps occur
 - e.g., if only one convex object is shown
- order of depicted objects (overlapping)
with only back face culling still depends on rendering sequence
→ idea for real HSR technique

HSR: Painter's Algorithm

- new approach to hidden surface removal (borrowed from van Gogh & co): draw scene from back to front
- sort scene's triangles from back to front
- start rendering triangles from the back
- problems:
 - cyclic overlaps
 - performance: sorting is $O(n \log n)$

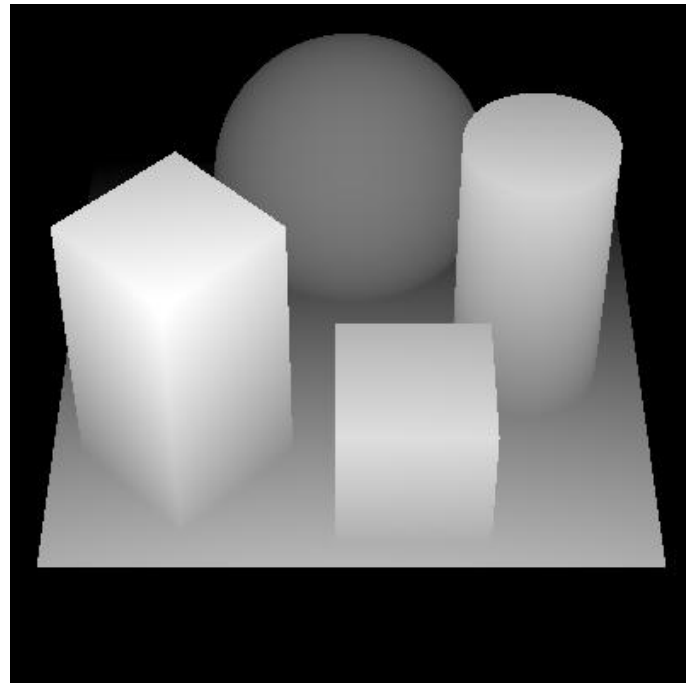
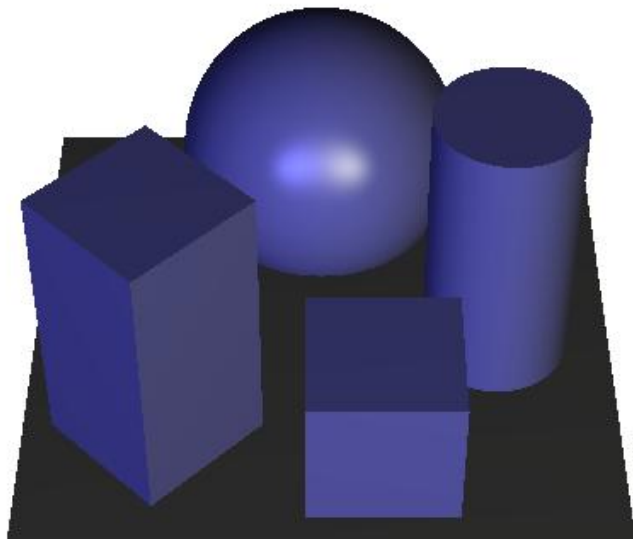


z-Buffering

- idea:
 - use advantages of Painter's algorithm (rendering from back to front)
 - avoid its disadvantages (e.g., need to sort & problems with cyclic triangles)
- realization by
 - trading speed for memory usage (memory is cheap [now anyway], time is not)
 - trading speed for accuracy (only compute what we really need/want)

z-Buffering

- introduce new pixel buffer: z-buffer (in addition to the frame buffer for image)
- z-buffer stores z-values of pixels



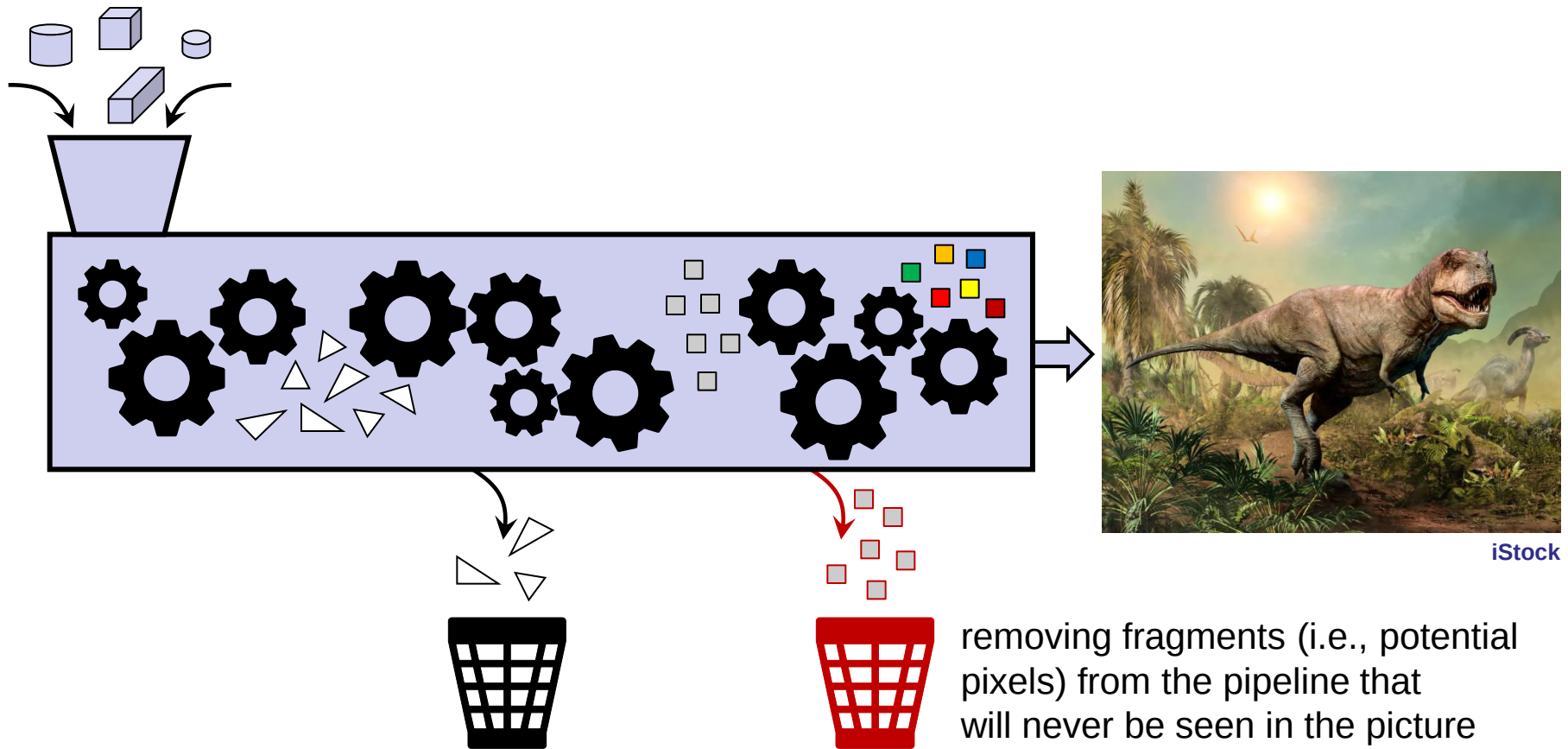
z-Buffering

- treat each primitive (triangle) individually:
scene $\rightarrow$ objects $\rightarrow$ triangles $\rightarrow$ pixels
- use z-buffer data to determine if a new triangle is (partially) hidden or not
- at each time, the part of scene that has been processed thus far is correctly displayed

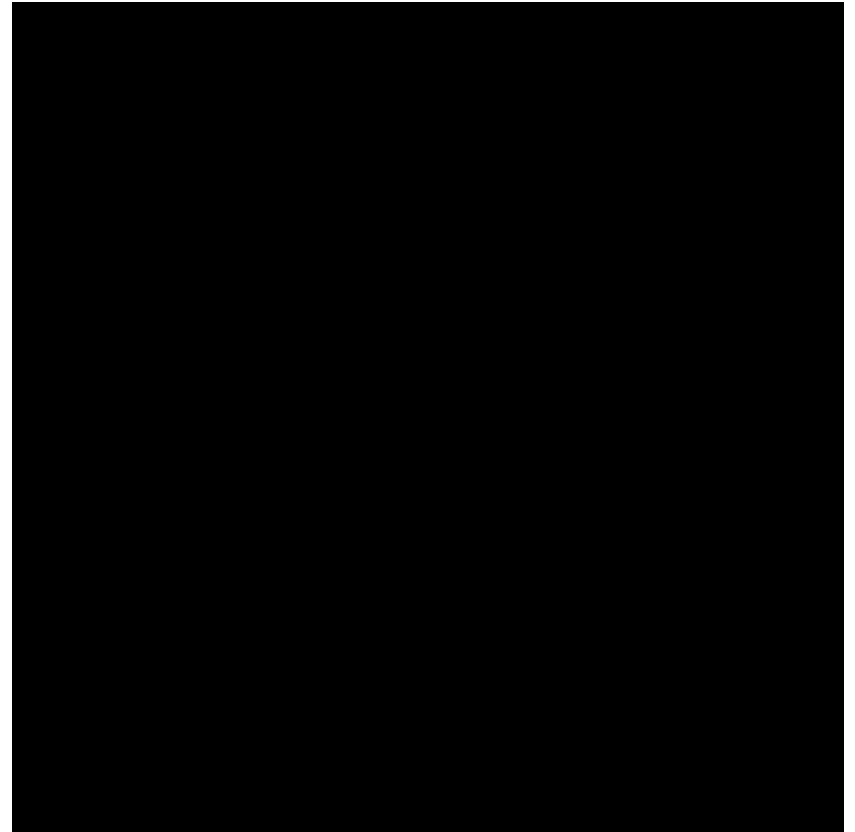
z-Buffering: Algorithm

- initialize z-buffer and frame buffer
- for each triangle
 - project all vertices of the triangle
 - interpolate z-values for each pixel (scan line)
 - before shading a pixel, test if its z-value is closer to camera (i.e. higher) than the current z-buffer value
 - if so: update z-buffer value and shade pixel
 - otherwise: discard pixel and continue
- after scene processing z-buffer contains depth map of scene

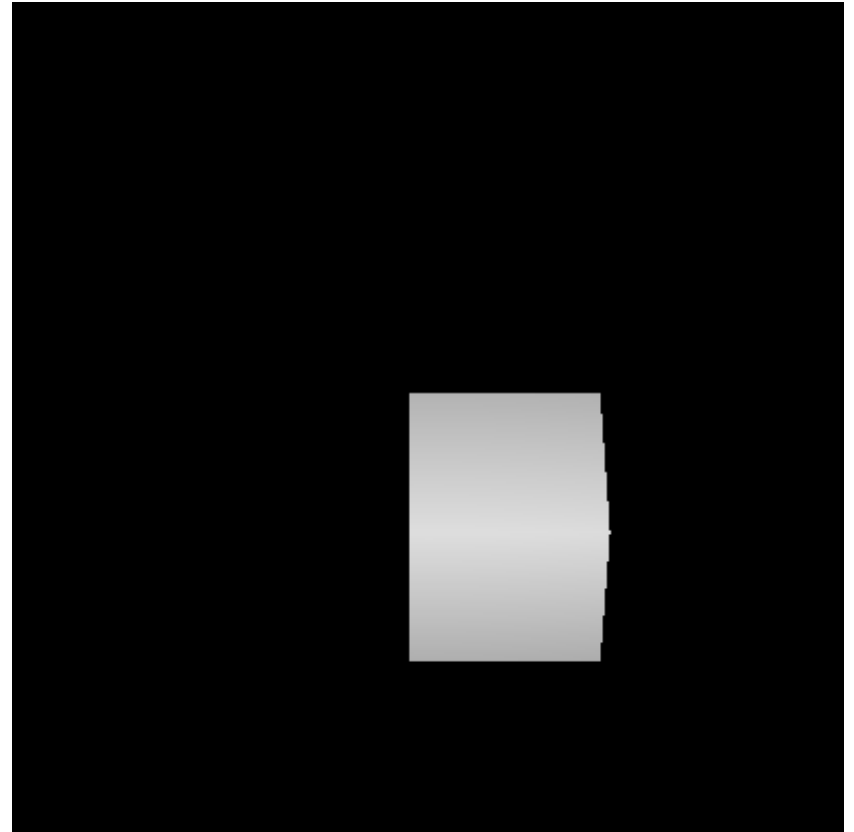
z-Buffering: Discarding pixels



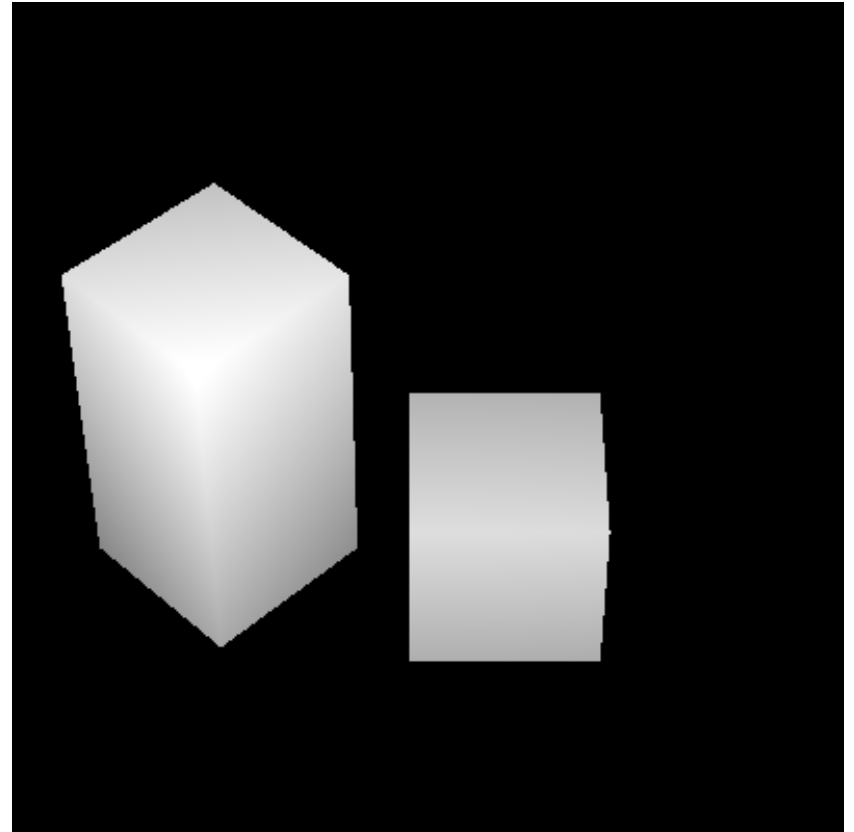
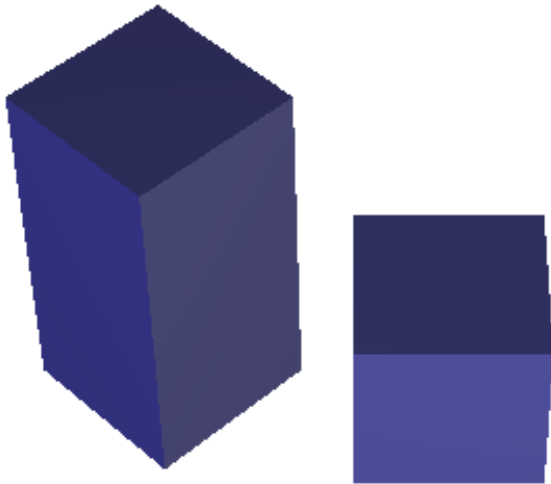
z-Buffering: Example (shown by object)



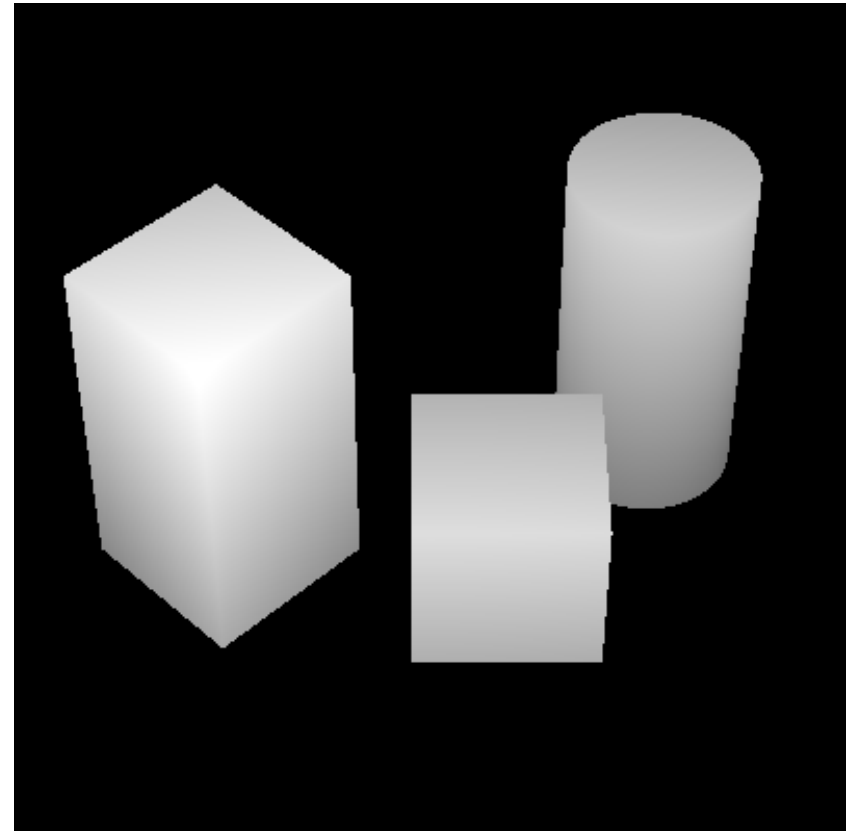
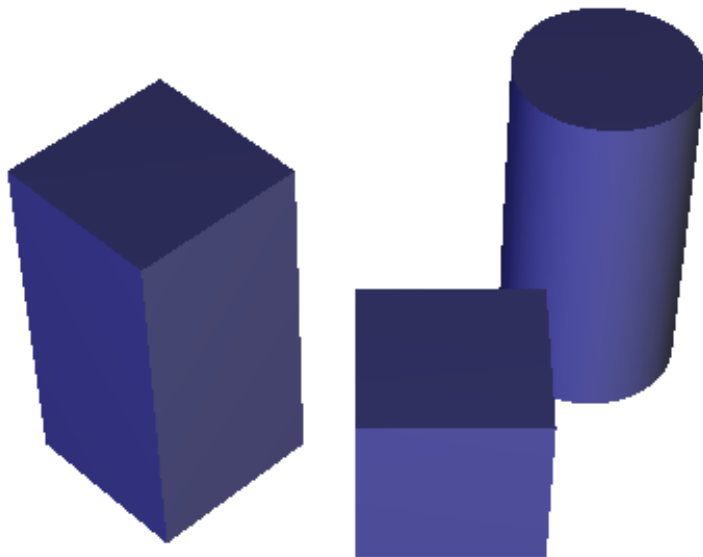
z-Buffering: Example (shown by object)



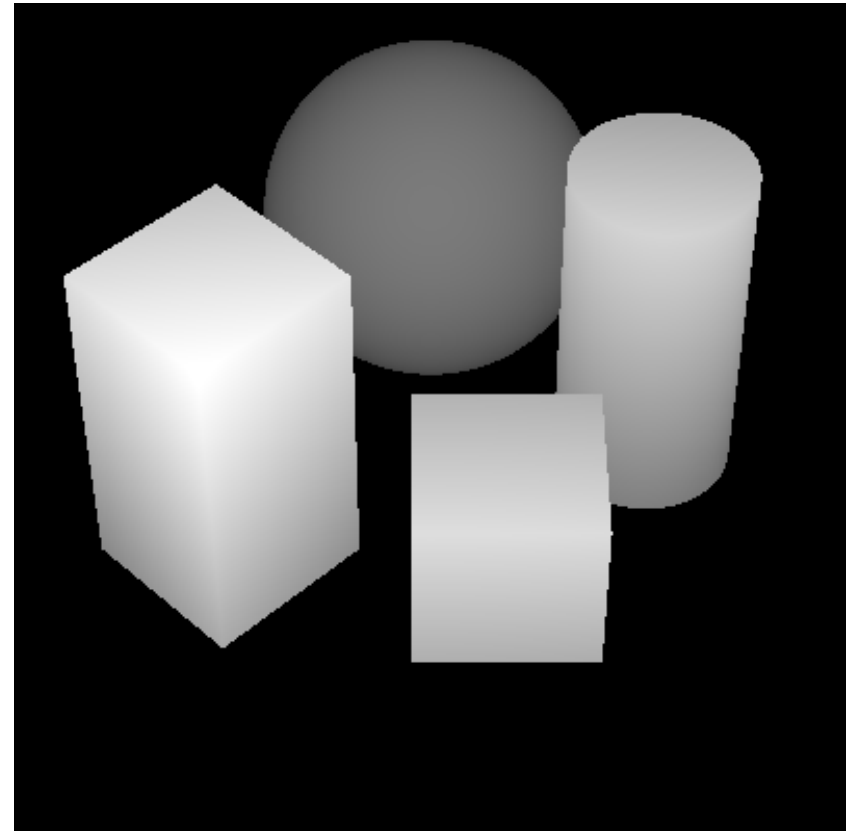
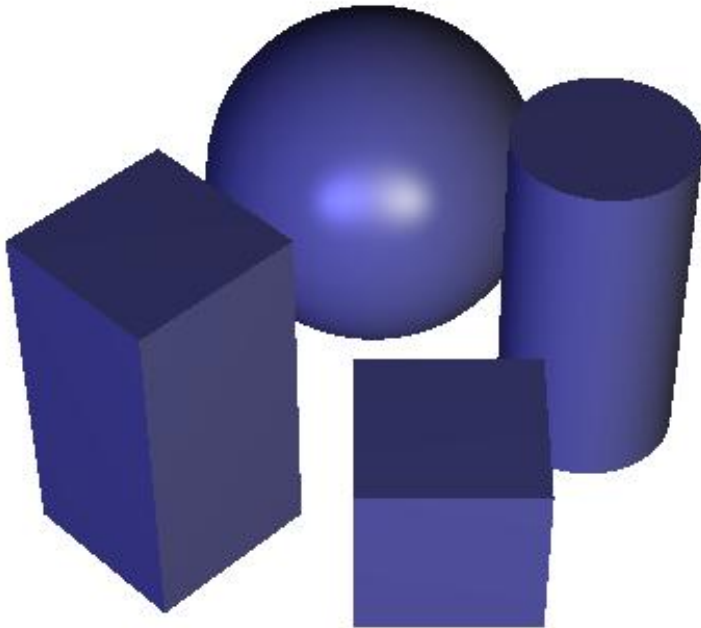
z-Buffering: Example (shown by object)



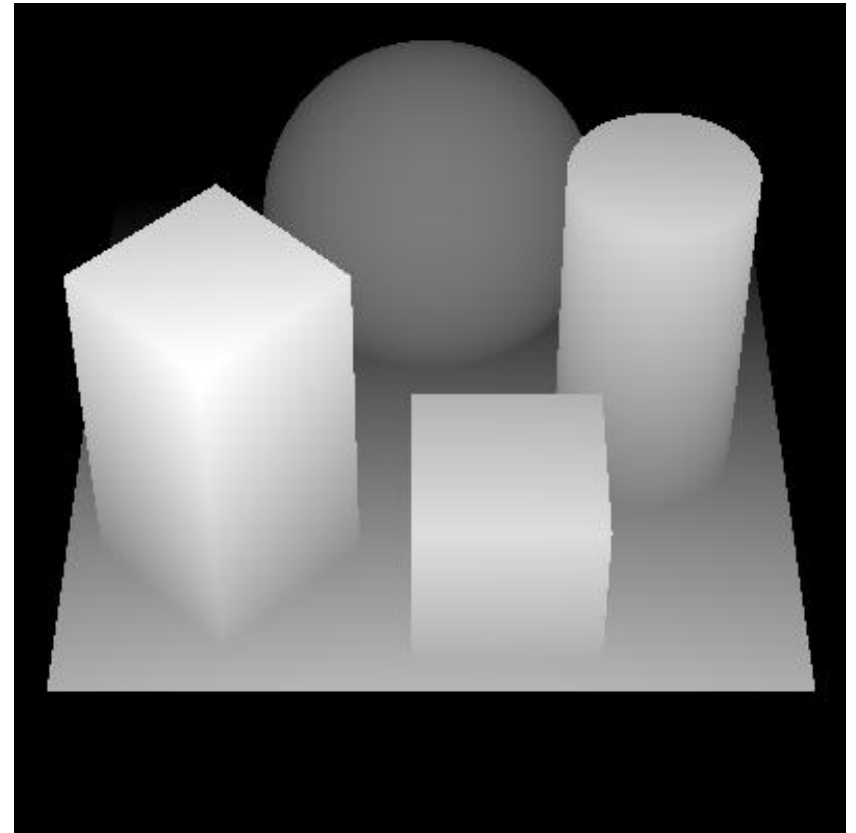
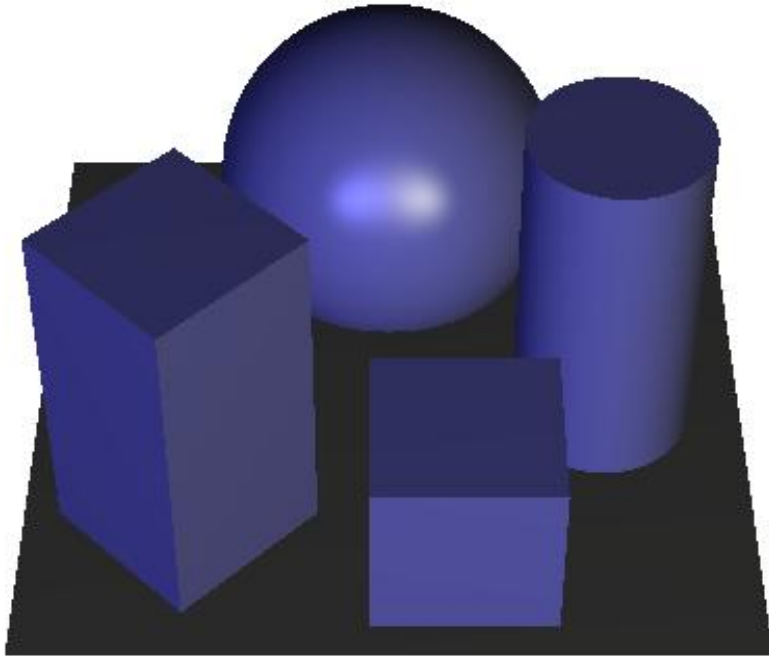
z-Buffering: Example (shown by object)



z-Buffering: Example (shown by object)



z-Buffering: Example (shown by object)



In reality the z-buffering treats the model triangle by triangle, not object by object!

z-Buffering

- advantages
 - can be implemented in hardware
 - can process infinitely many primitives
 - does not need sorting of primitives
(only need to know distance to camera)
 - can handle cyclic and penetrating triangles
- disadvantages
 - needs memory to keep all z-values
(image size @ 8bit or 16bit)
 - cannot handle transparency properly

Other HSR Algorithms

- hierarchical z-buffer
 - smaller versions in faster GPU memory (cache)
 - stores most distant z-depth
 - most fragments will be rejected anyway
 - faster simple rejection for many of them



Other HSR Algorithms

- hierarchical z-buffer
- Appel's algorithm (for lines)
- Warnock's algorithm
- Octrees
- Binary Space Partitioning (BSP-trees)
- A-buffer (with anti-aliasing)
- etc.

Hidden Surface Removal – Summary

- needed to reduce rendering effort
- backface culling
 - remove all triangles that point away
 - not sufficient as HSR
- z-buffering
 - use of additional z-buffer
 - pixel-based technique
 - no polygon sorting needed
 - only pixel accuracy